



Current measurement in e-mobility

CSM Web Seminars



CSM **Xplained**
measurement technology

Innovative Measurement and Data Technology

Current measurement in e-mobility

- ▶ Agenda
 - Basics
 - Measurement Technology
 - Application examples



Current measurement in e-mobility

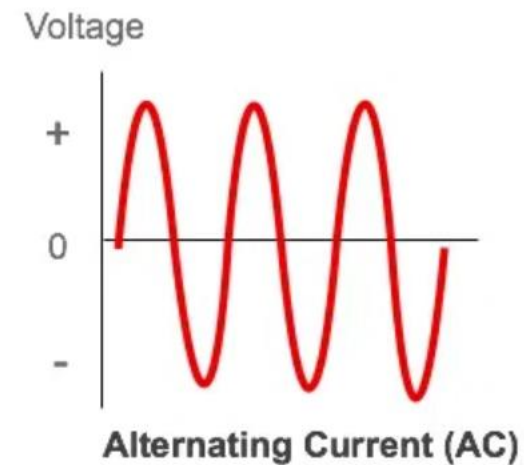
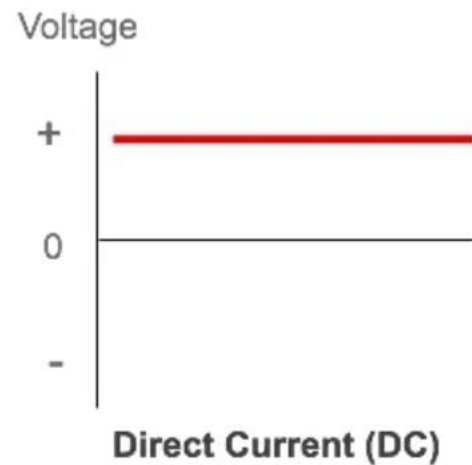
- ▶ Agenda
 - **Basics**



Measure electric current

Electric current, known from literature, study, internet, practice

- ▶ Direct current (DC)
- ▶ Alternating current (AC)
- ▶ Mixed or variable current

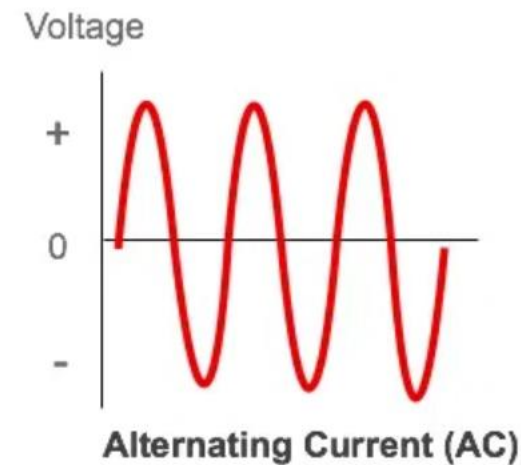
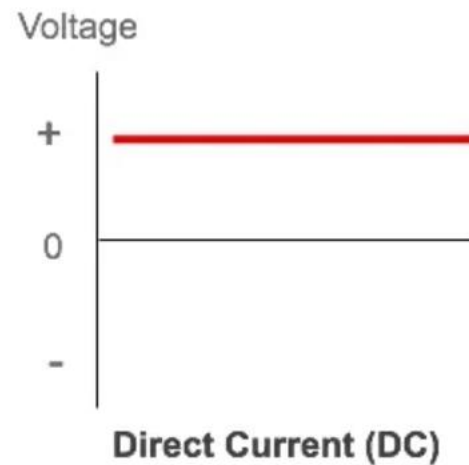


Measure electric current

Electric current, known from literature, study, internet, practice

- ▶ Direct current (DC)
- ▶ Alternating current (AC)
- ▶ Mixed or variable current

Ammeters = current meters = ampere meters



Measure electric current

Electric current, known from literature, study, internet, practice

- ▶ Direct current (DC)
- ▶ Alternating current (AC)
- ▶ Mixed or variable current

Ammeters = current meters = ampere meters

Measuring transducer: Measure I , output I or U or ...

Measuring converter: Measure I , output on digital bus



Measure electric current

Electric current, known from literature, study, internet, practice

- ▶ Direct current (DC)
- ▶ Alternating current (AC)
- ▶ Mixed or variable current

Ammeters = current meters = ampere meters

Measuring transducer: Measure I , output I or U or ...

Measuring converter: Measure I , output on digital bus

Popular Current Sensors:

- ▶ Current clamp, hinged transformer, closed ring
- ▶ Shunts, hall sensors, zero flux transducers, Rogowski coils
- ▶ Sampling Rate, bandwidth



Where do currents occur on the cables?

- ▶ Inner conductor
 - Large variable parts of the current?



Where do currents occur on the cables?

- ▶ Inner conductor
 - Large variable parts of the current?
- ▶ Braided Shield



Where do currents occur on the cables?

- ▶ Inner conductor
 - Large variable parts of the current?
- ▶ Braided Shield
- ▶ Shield currents
 - Usually between inverter and E-machine
 - Between inverter and braking resistor



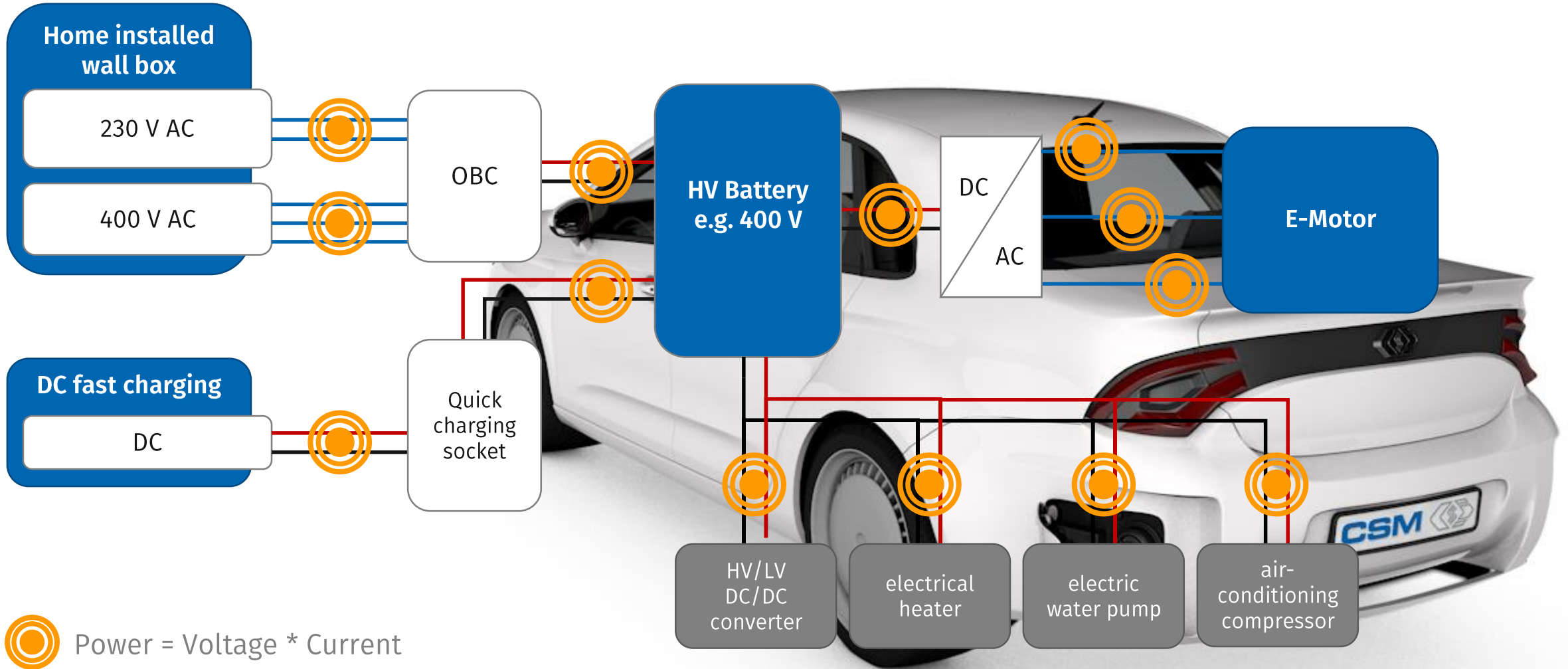


Where do currents occur on the cables?

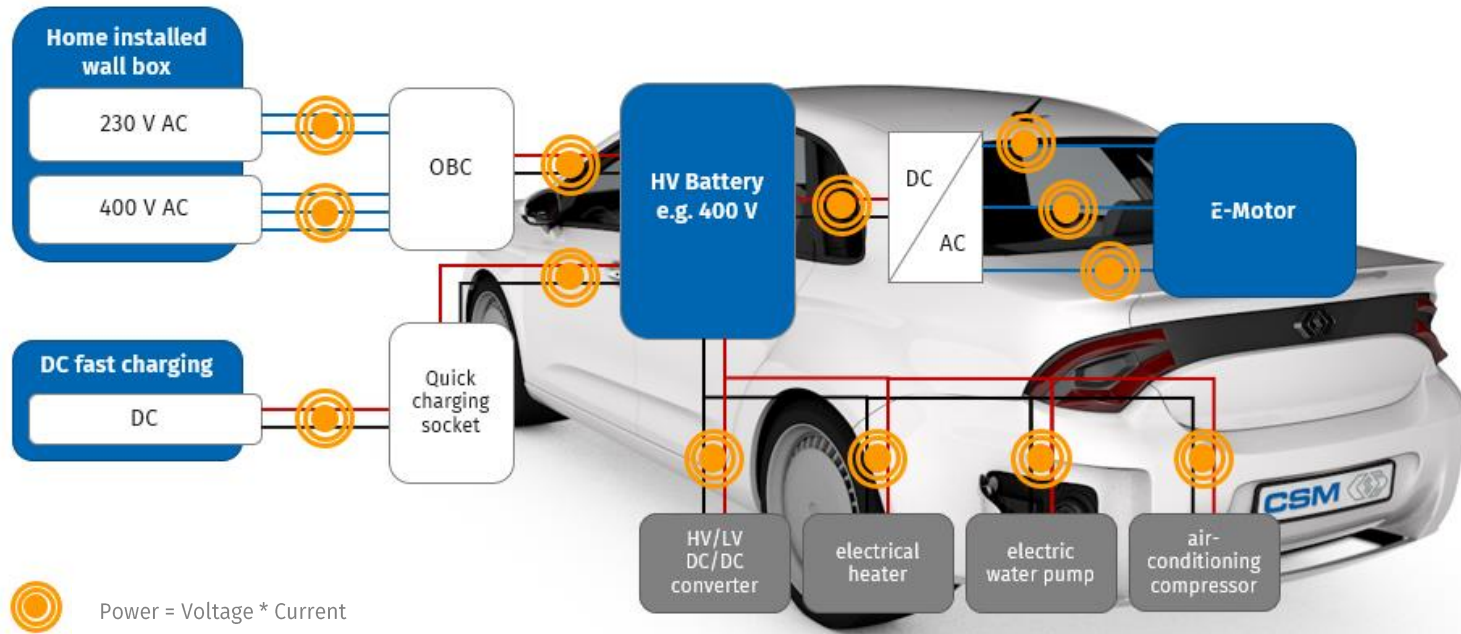
- ▶ Inner conductor
 - Large variable parts of the current?
- ▶ Braided Shield
- ▶ Shield currents
 - Usually between inverter and E-machine
 - Between inverter and braking resistor
- ▶ Potential effects
 - Burnt contacts
 - Scorched shields?



Power Measurements in EV High-Voltage Electrical Systems



Electric current in electromobility



Charging System(s) feed the HV Battery

HV battery feeds consumers

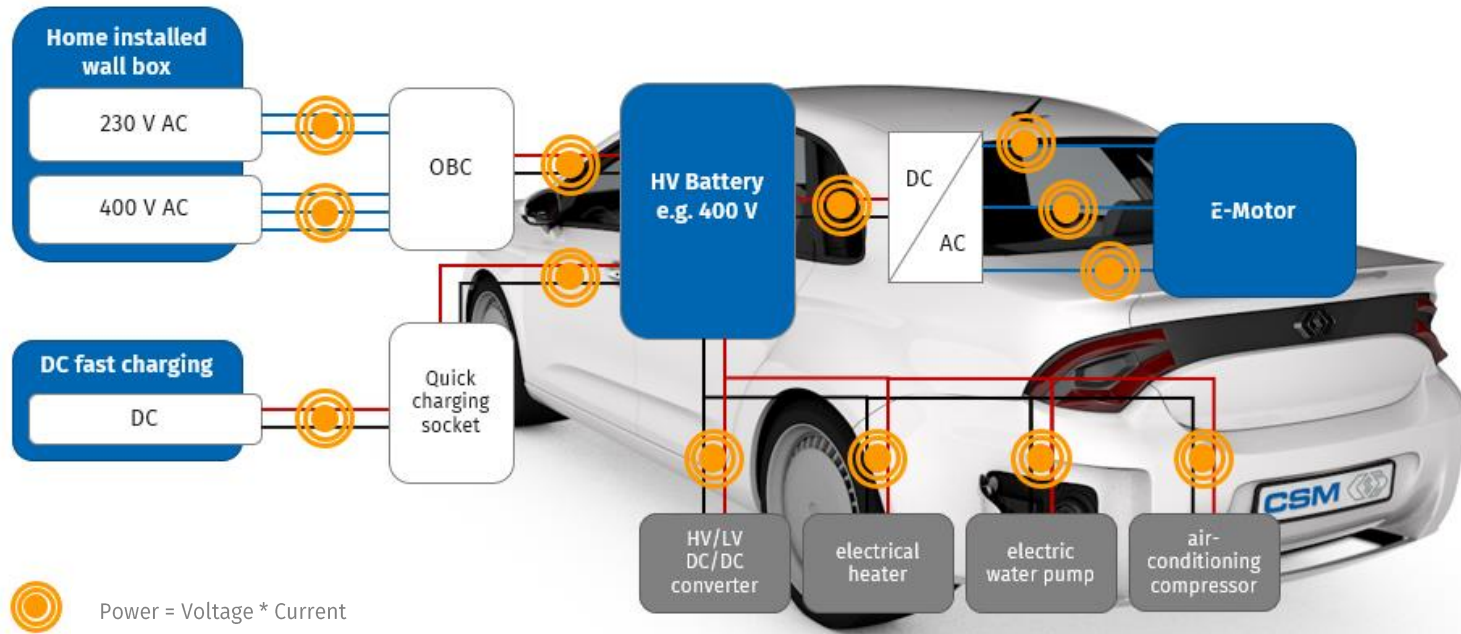
▶ Inverter -> E-machine

▶ Small consumers

Current results from PWM-controlled voltage

Small consumers have built-in PWM control

Electric current in electromobility



Charging System(s) feed the HV Battery

HV battery feeds consumers

▶ Inverter -> E-machine

▶ Small consumers

Current results from PWM-controlled voltage

Small consumers have built-in PWM control

Current is never only direct current

Current has alternating components

Current measurement in e-mobility

► Agenda

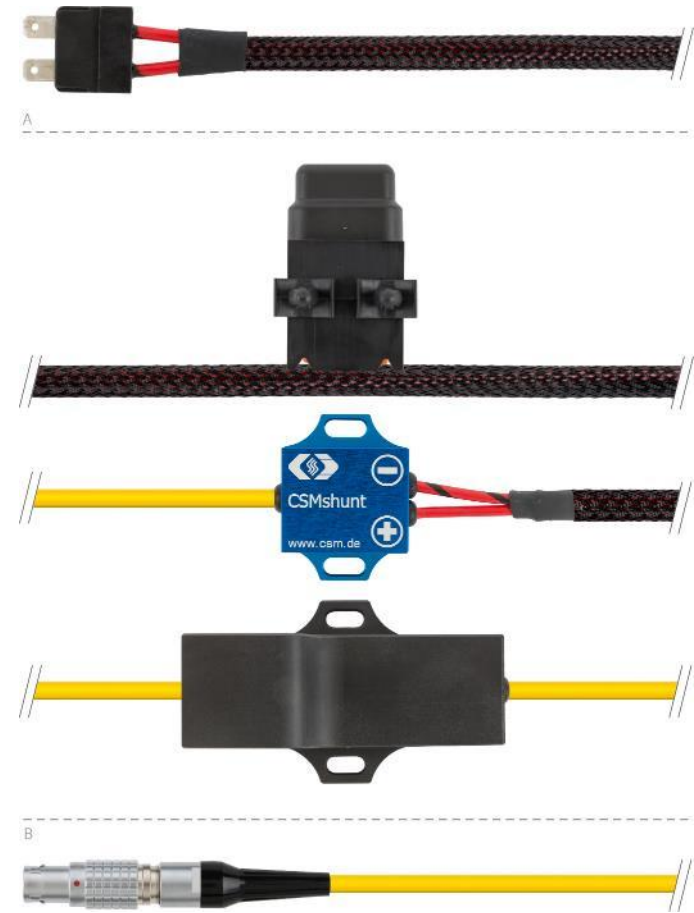
- Basics
- **Measurement Technology**



WLTC – Worldwide harmonized Light-duty vehicles Test Cycles EPA (Environmental Protection Agency) Drive Cycles

Fuel consumption in driving condition

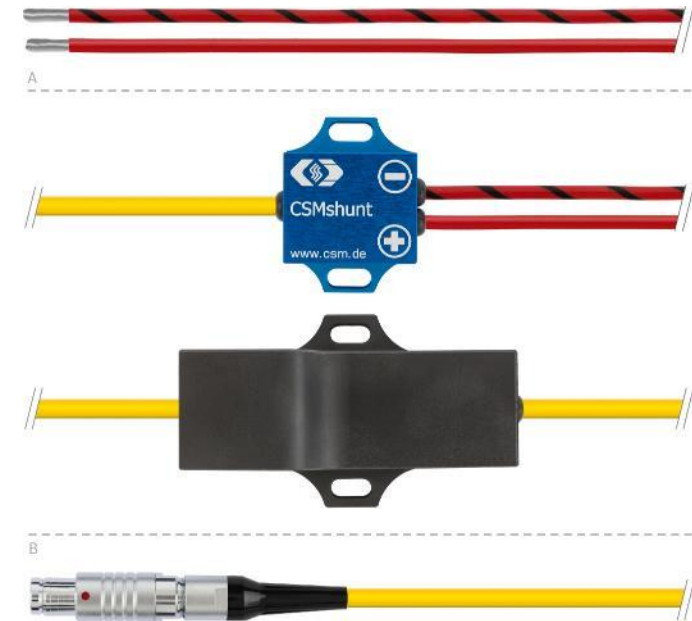
- ▶ Diesel, carburetor fuel
- ▶ ...
- ▶ Electrical energy E [kWh]
- ▶ Electrical work W [kWh]
- ▶ Battery energy $E = Q * U$
- ▶ $I(t) = dQ / dt$
 - LV-Batterie $\pm 2.5 \text{ A} .. \pm 1,500 \text{ A}$



WLTC – Worldwide harmonized Light-duty vehicles Test Cycles EPA (Environmental Protection Agency) Drive Cycles

Fuel consumption in driving condition

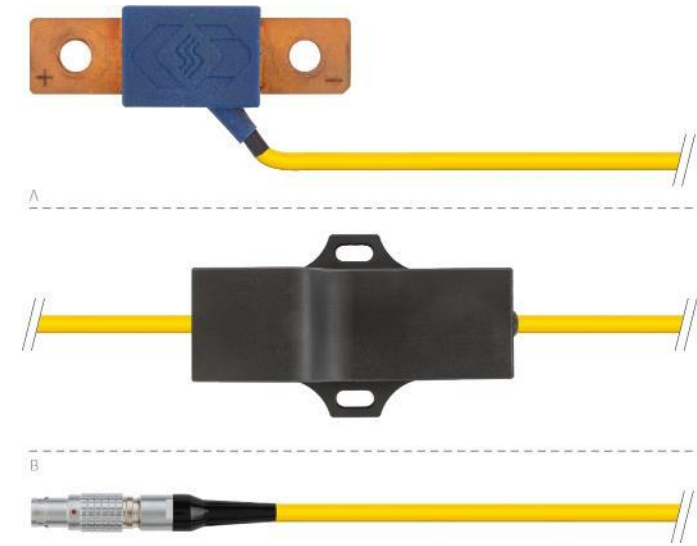
- ▶ Diesel, carburetor fuel
- ▶ ...
- ▶ Electrical energy E [kWh]
- ▶ Electrical work W [kWh]
- ▶ Battery energy $E = Q * U$
- ▶ $I(t) = dQ / dt$
 - LV-Batterie $\pm 2.5 \text{ A} .. \pm 1,500 \text{ A}$



WLTC – Worldwide harmonized Light-duty vehicles Test Cycles EPA (Environmental Protection Agency) Drive Cycles

Fuel consumption in driving condition

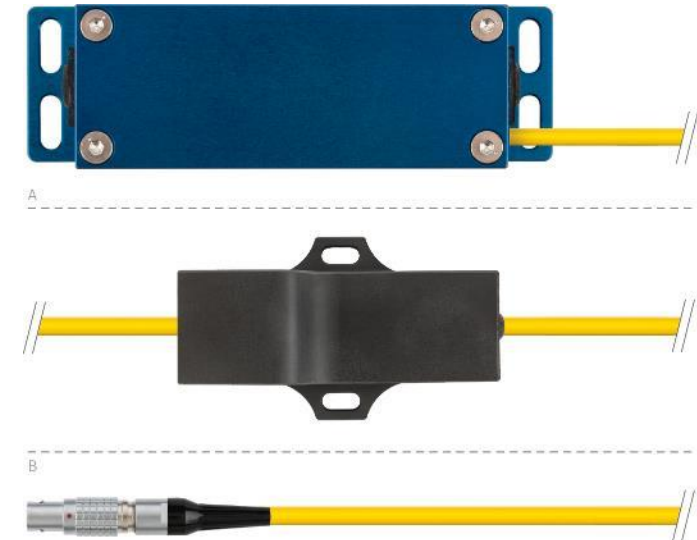
- ▶ Diesel, carburetor fuel
- ▶ ...
- ▶ Electrical energy E [kWh]
- ▶ Electrical work W [kWh]
- ▶ Battery energy $E = Q * U$
- ▶ $I(t) = dQ / dt$
 - LV-Batterie $\pm 2.5 \text{ A} .. \pm 1,500 \text{ A}$



WLTC – Worldwide harmonized Light-duty vehicles Test Cycles EPA (Environmental Protection Agency) Drive Cycles

Fuel consumption in driving condition

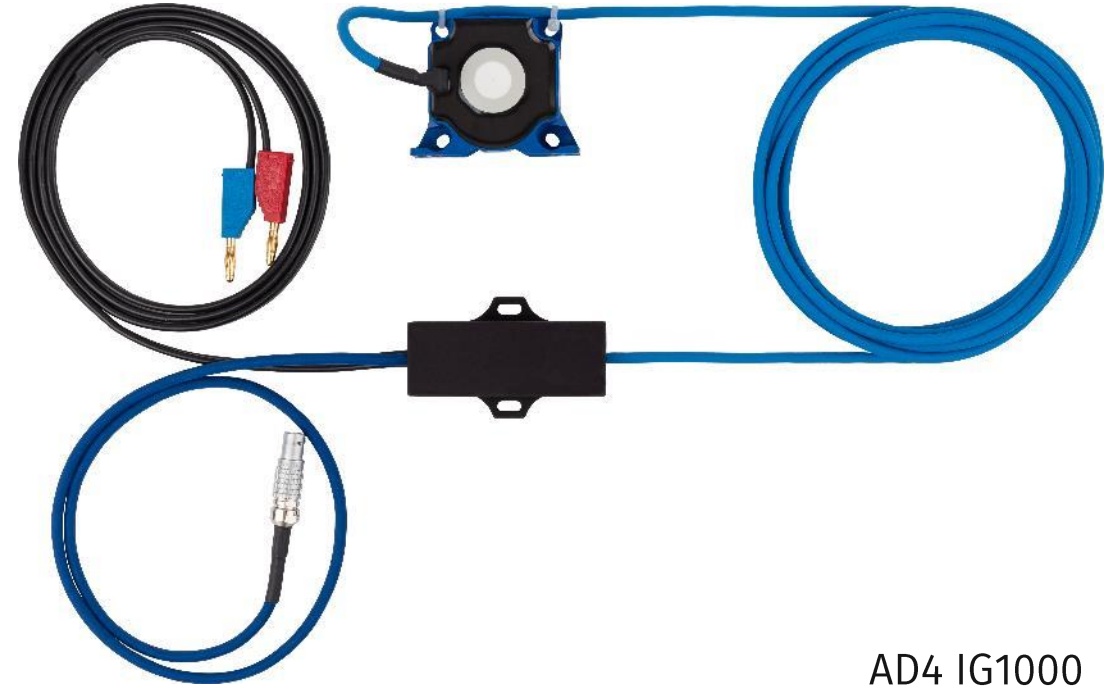
- ▶ Diesel, carburetor fuel
- ▶ ...
- ▶ Electrical energy E [kWh]
- ▶ Electrical work W [kWh]
- ▶ Battery energy $E = Q * U$
- ▶ $I(t) = dQ / dt$
 - LV-Batterie $\pm 2.5 \text{ A} .. \pm 1,500 \text{ A}$



LEM sensor packages by CSM ≥ 100 kHz

Current measurements

- ▶ Wide variety of measuring ranges
 - ± 5 A .. $\gg \pm 1000$ A
- ▶ Integrated DC supply
 - 9 V .. 36 V
- ▶ Measurement of U_{out} with fast AD converter
- ▶ Parameterization and calibration data in TEDS chip

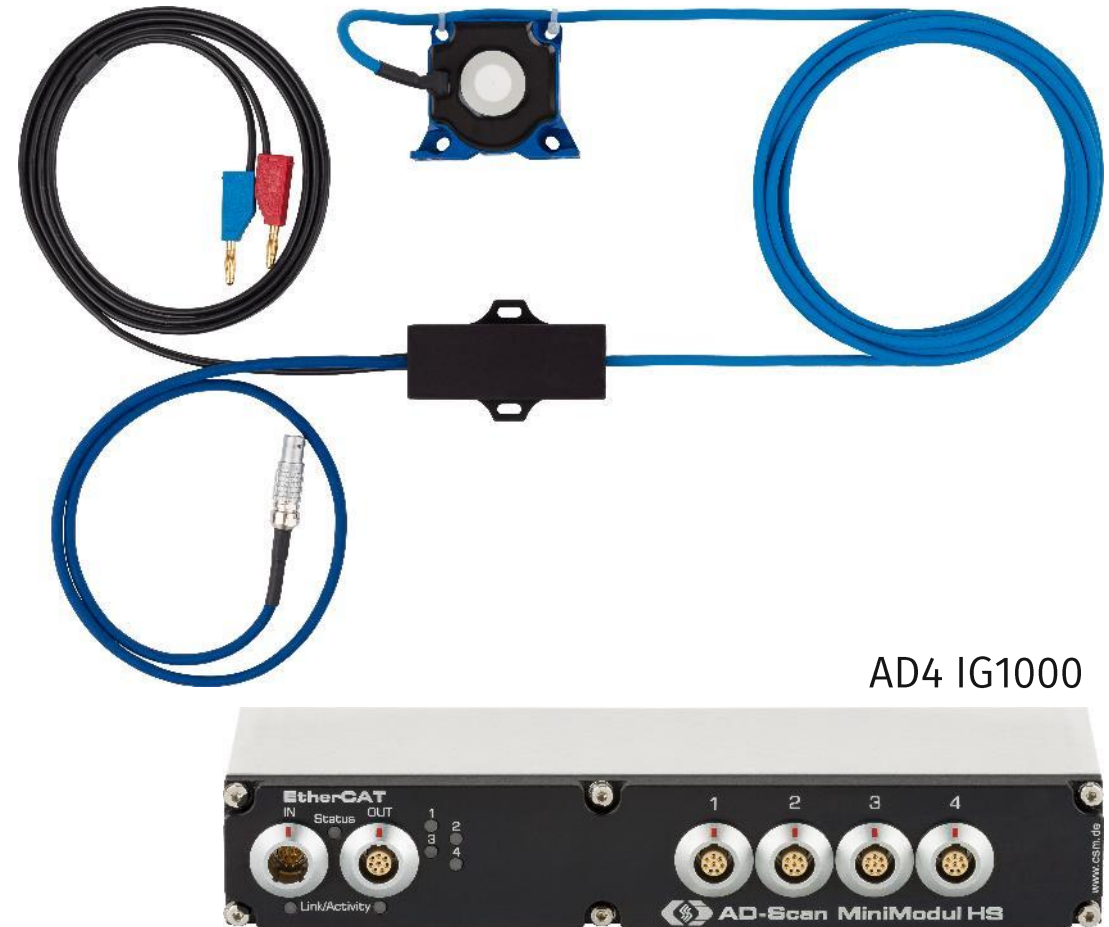


LEM sensor packages by CSM ≥ 100 kHz

Current measurements

- ▶ Wide variety of measuring ranges
 - ± 5 A .. $\gg \pm 1000$ A
- ▶ Integrated DC supply
 - 9 V .. 36 V
- ▶ Measurement of U_{out} with fast AD converter
- ▶ Parameterization and calibration data in TEDS chip

- ▶ (HV) connector does not fit through LEM
- ▶ I_{mess} = shield current + inner conductor
- ▶ Latency



CSM AD converter and transducer from HIOKI, DC ... ≥ 100 kHz

Current measurements with clamp

- ▶ Various measuring ranges
- ▶ Measurement of U_{out} with fast AD converter
- ▶ Limited temperature range
- ▶ Suitable for use in vehicle?
 - Test bench
 - Road test

- ▶ I_{mess} = shield current + inner conductor



AD4 IG1000



CSM HV Breakout Modules (HV BM) for measuring I and U, calculating P

There are different HV safe modules

- ▶ For single phase measurements of Current
 - Shunt inserts, I_{nom} :
 ± 50 A, ± 125 A, ± 250 A, ± 500 A, ± 800 A
 - I_{Peak} up to $\pm 1,400$ A
 - Voltage :
Up to 1000 V (working) and 2000 V (peaks)
- ▶ 1 MHz Sampling per channel
- ▶ Outputs I, U, P
 - EtherCAT and CAN



HV BM 1.2
=
1 Phase
2 PG's

CSM HV Breakout Modules (HV BM) for measuring I and U, calculating P


Current measured via **Shunts**

- ▶ Calibration data stored in the chip
- ▶ Temperature compensated
- ▶ Adjustment to the measuring range
- ▶ IP67 Enclosure and EN61010 safe



HV BM 1.1
=
1 Phase
1 PG



 PA (Potential equalization)

CSM HV Breakout Modules – Flexible Variants

5 Module Options

- ▶ **HV BM 1.1** = 1 Phase, 1 HV Cable (V+, V- common insulation)



HV BM 1.1

CSM HV Breakout Modules – Flexible Variants

5 Module Options

- ▶ **HV BM 1.1** = 1 Phase, 1 HV Cable (V+, V- common insulation)
- ▶ **HV BM 1.2** = 1 Phase, 2 HV Cables (V+, V- Separate insulation)



HV BM 1.1



HV BM 1.2

CSM HV Breakout Modules – Flexible Variants

5 Module Options

- ▶ **HV BM 1.1** = 1 Phase, 1 HV Cable (V+, V- common insulation)
- ▶ **HV BM 1.2** = 1 Phase, 2 HV Cables (V+, V- Separate insulation)
- ▶ **HV BM 1.2 +S** = HV BM 1.2 + measuring HV Cable Shield currents



HV BM 1.1



HV BM 1.2



HV BM 1.2 +S

CSM HV Breakout Modules – Flexible Variants

5 Module Options

- ▶ **HV BM 1.1** = 1 Phase, 1 HV Cable (V+, V- common insulation)
- ▶ **HV BM 1.2** = 1 Phase, 2 HV Cables (V+, V- Separate insulation)
- ▶ **HV BM 1.2 +S** = HV BM 1.2 + measuring HV Cable Shield currents
- ▶ **HV BM 3.1** = 3 Phases, 1 Cable (V+, V- common insulation)
- ▶ **HV BM 3.3** = 3 Phase, 3 Cables (3 * Separate Insulation)
+ Integrated XCP-Gateway

NEW

SOON



HV BM 1.1



HV BM 1.2



HV BM 3.1



HV BM 1.2 +S

CSM HV Breakout Modules – Flexible Variants

5 Module Options

- ▶ **HV BM 1.1** = 1 Phase, 1 HV Cable (V+, V- common insulation)
- ▶ **HV BM 1.2** = 1 Phase, 2 HV Cables (V+, V- Separate insulation)
- ▶ **HV BM 1.2 +S** = HV BM 1.2 + measuring HV Cable Shield currents
- ▶ **HV BM 3.1** = 3 Phases, 1 Cable (V+, V- common insulation)
- ▶ **HV BM 3.3** = 3 Phase, 3 Cables (3 * Separate Insulation)
+ Integrated XCP-Gateway



HV BM 1.1



HV BM 1.2



HV BM 3.1



HV BM 1.2 +S

Test-bench

- ▶ Easy integration into test automation system

In-Vehicle

- ▶ IP67, -40°C to +125°C

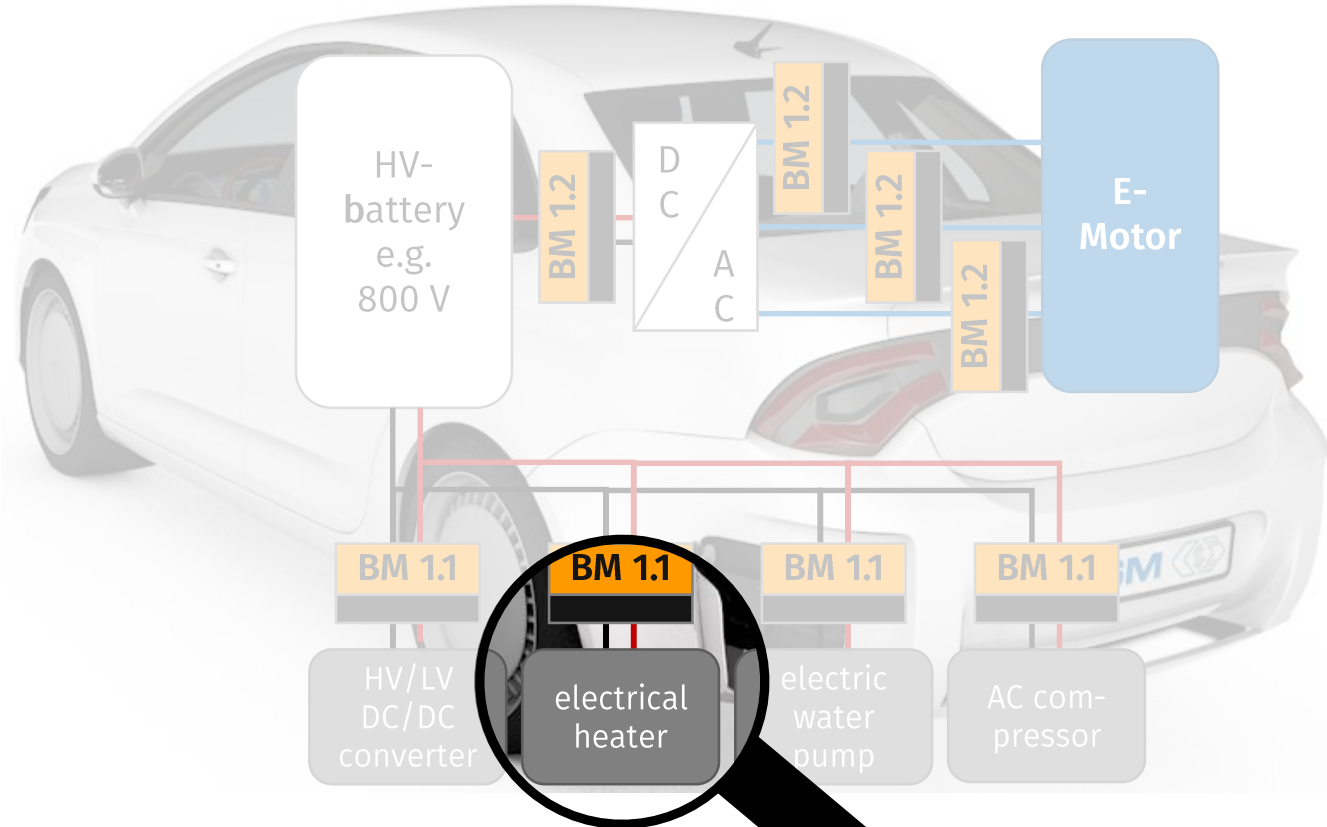
Simplified and Consistent tool-chain (hw and sw) throughout development process

Current measurement in e-mobility

- ▶ Agenda
 - Basics
 - Measurement Technology
 - **Application examples**



Electric current in electromobility



HV battery feeds consumer

- ▶ Inverter -> E-machine
- ▶ Small consumer

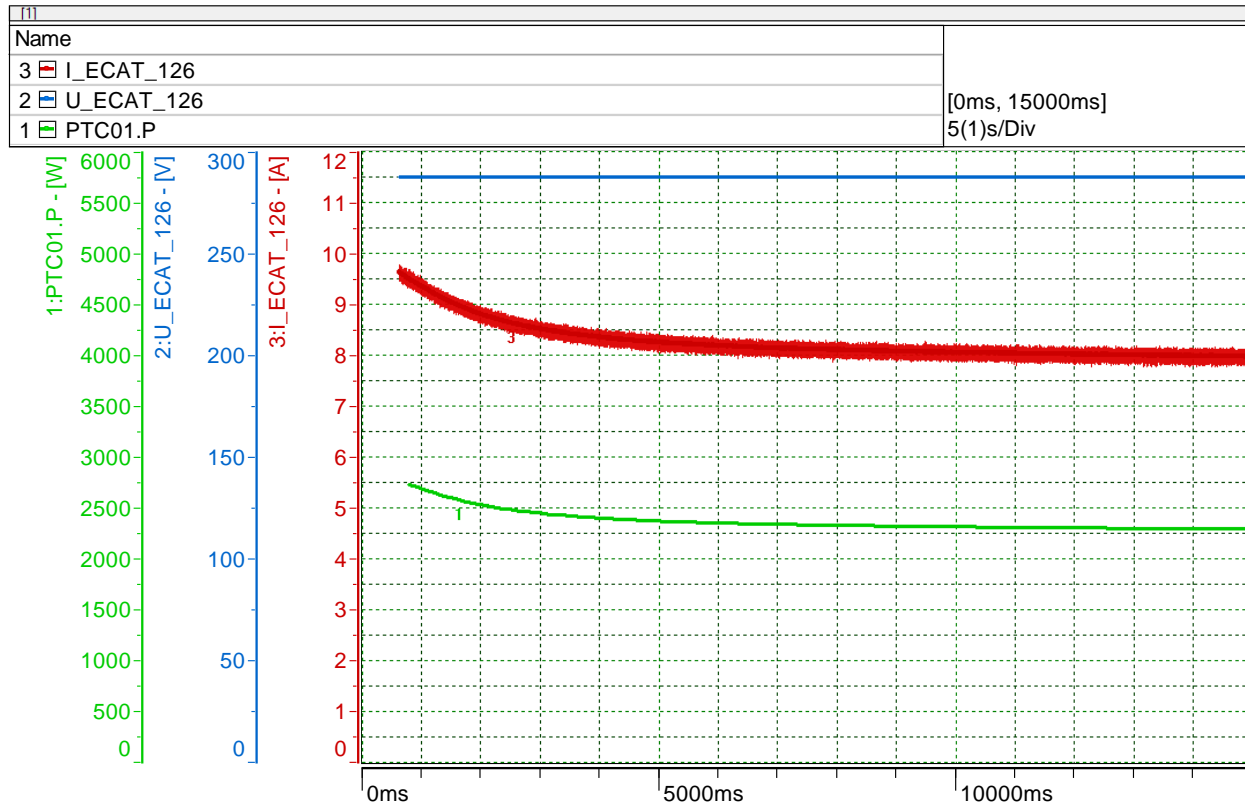
Current results from PWM-controlled voltage

Small consumers have built-in PWM control

Current is never only direct current

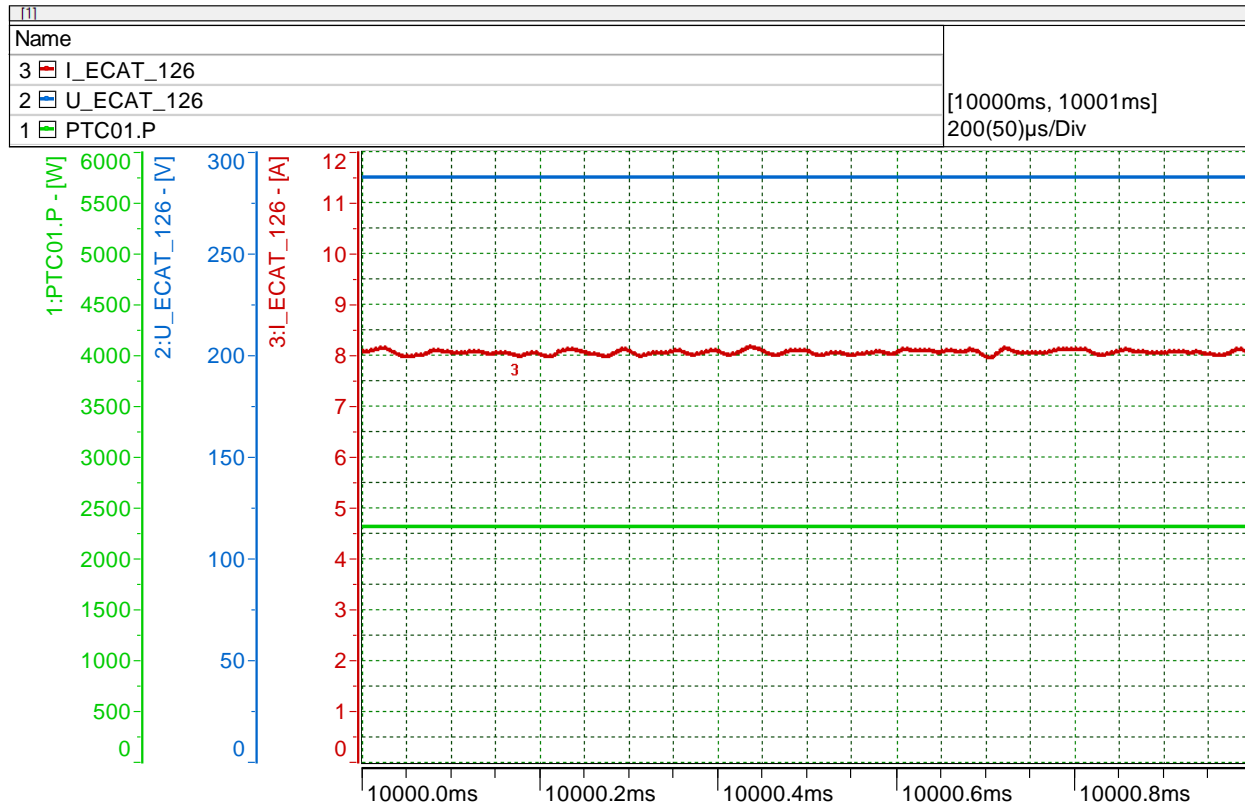
Current has alternating components

PTC-Electrical Heater



- ▶ Stable supply voltage
- ▶ Heating element heats up
- ▶ Current and power decrease at the beginning

PTC-Electrical Heater

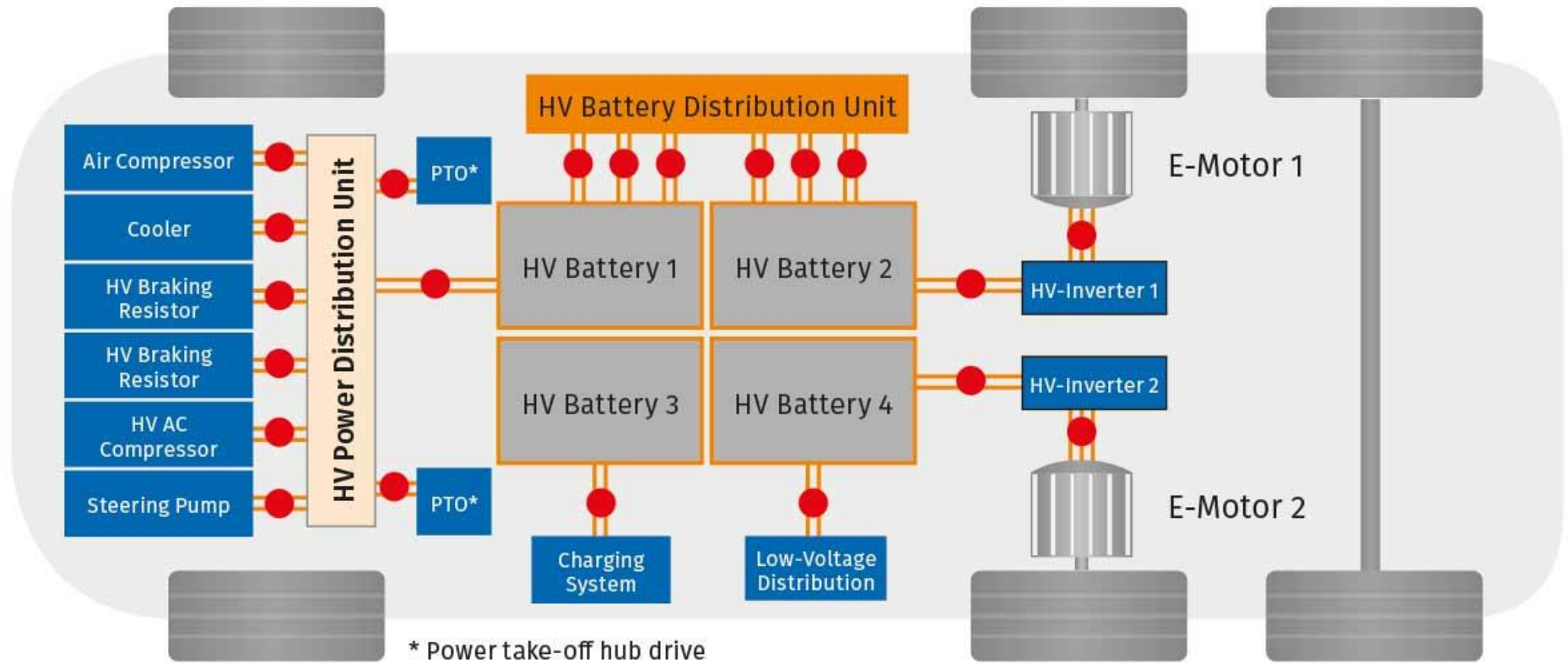


Heating power is PWM controlled

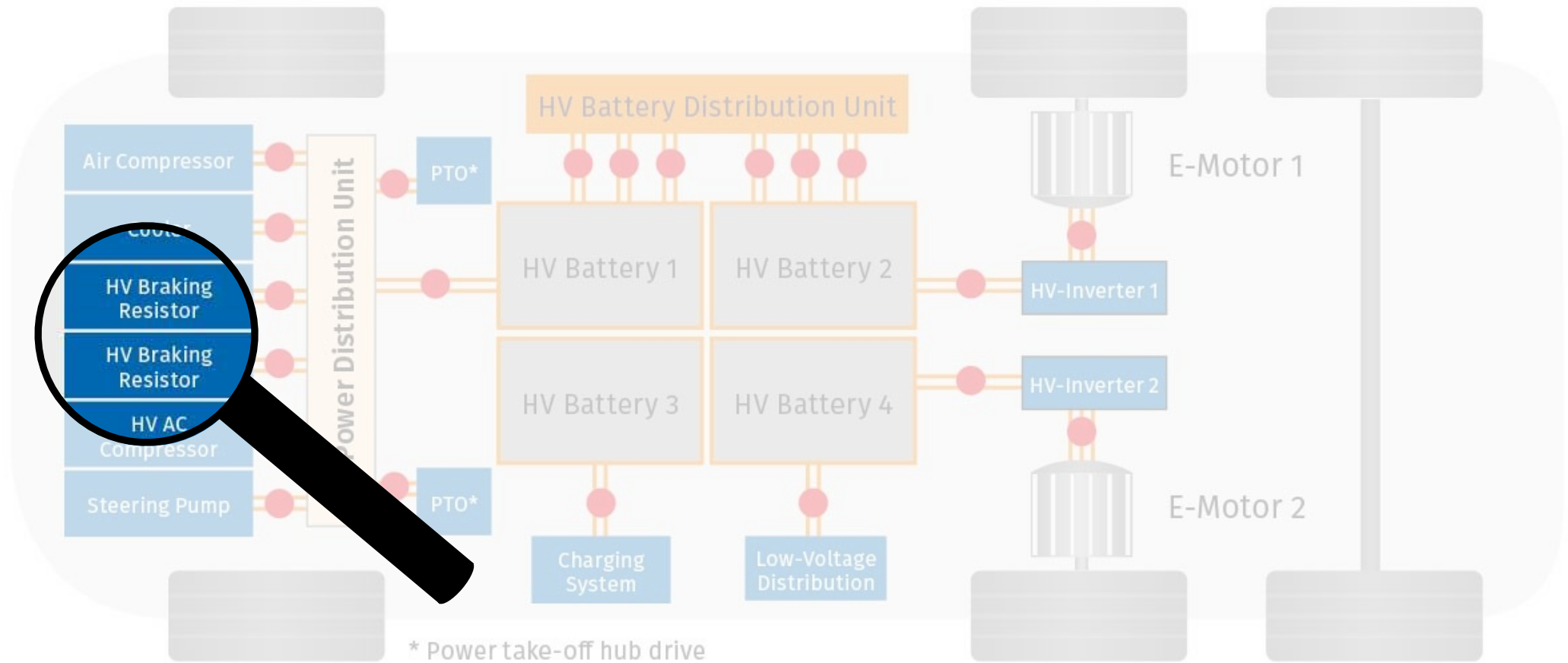
Well designed buffer capacitor

- ▶ Little feedback on the supply voltage
- ▶ Little ripple in current consumption

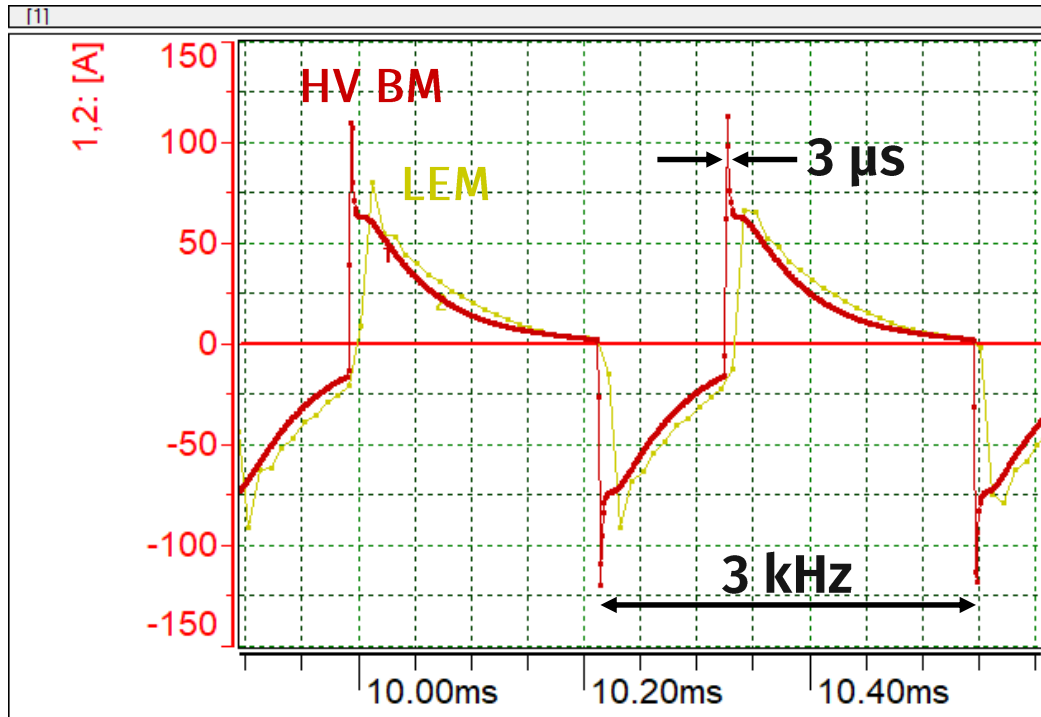
Commercial vehicle, HV electrical system



Commercial vehicle, HV electrical system



Braking resistor, measurement of shield current



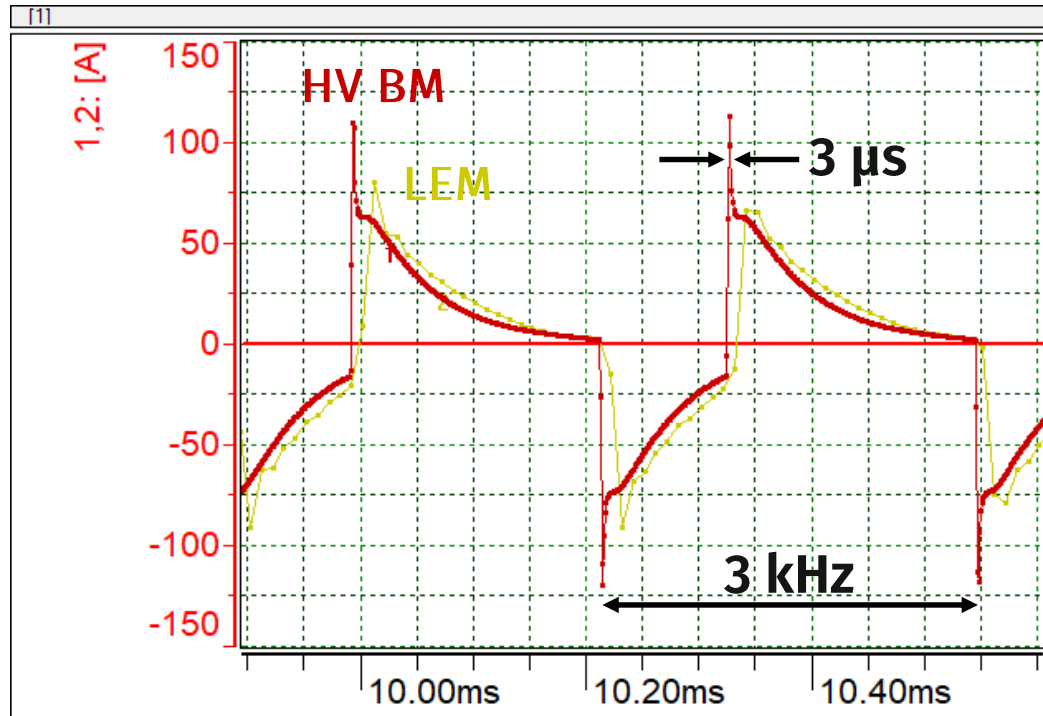
PWM controlled braking power

3 kHz basic system frequency

HV BM

▶ Captures Spikes of 3 μs

Braking resistor, measurement of shield current



Measured, maximum shield currents :

- ▶ I_{\max} : LEM = 90 A | HV BM = 120 A

PWM controlled braking power

3 kHz basic system frequency

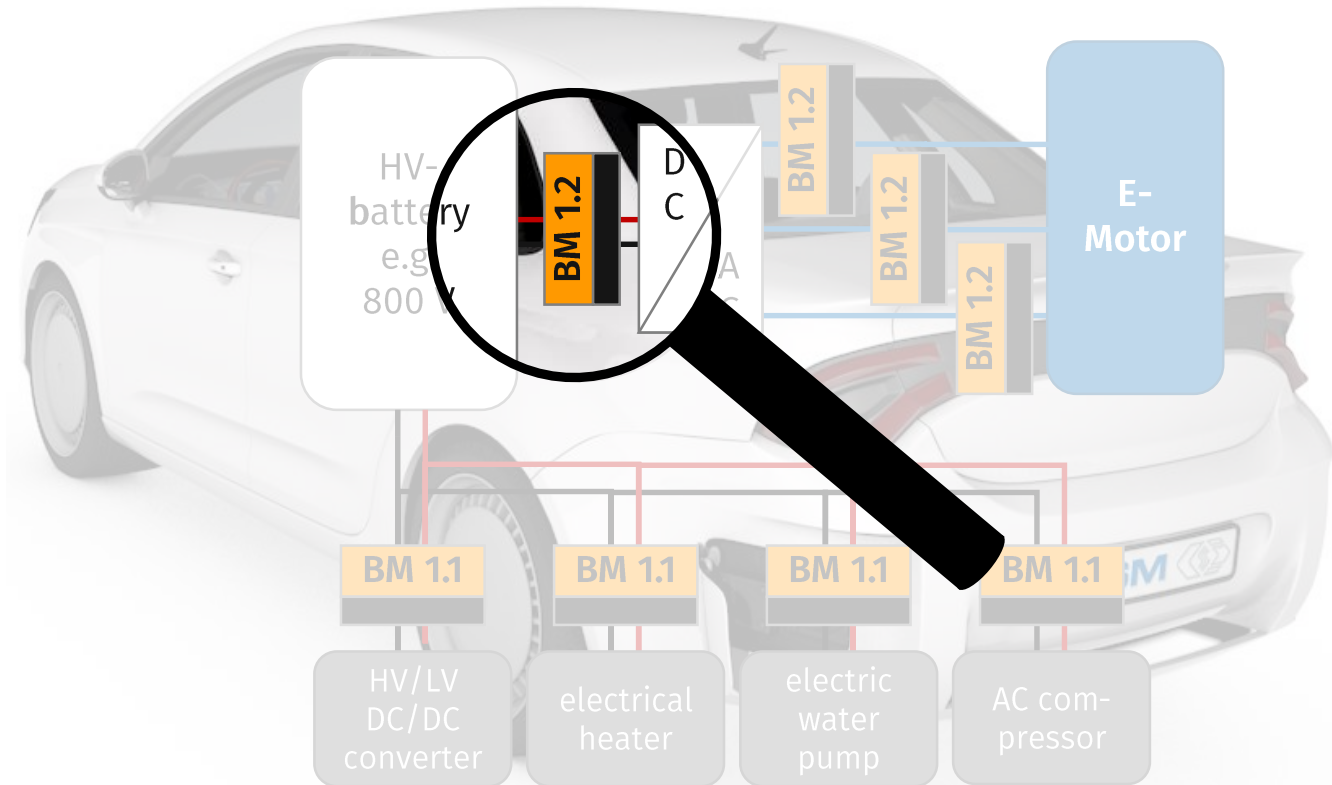
HV BM

- ▶ Captures Spikes of 3 μ s

LEM Sensor Package + AD4 IG1000

- ▶ measurement bandwidth too small to resolve peaks
- ▶ Spike latency of $\sim 20 \mu$ s
- ▶ Measures only 75% of peak current

Electric current in electromobility



HV battery feeds consumer

- ▶ Inverter -> E-machine
- ▶ Small consumer

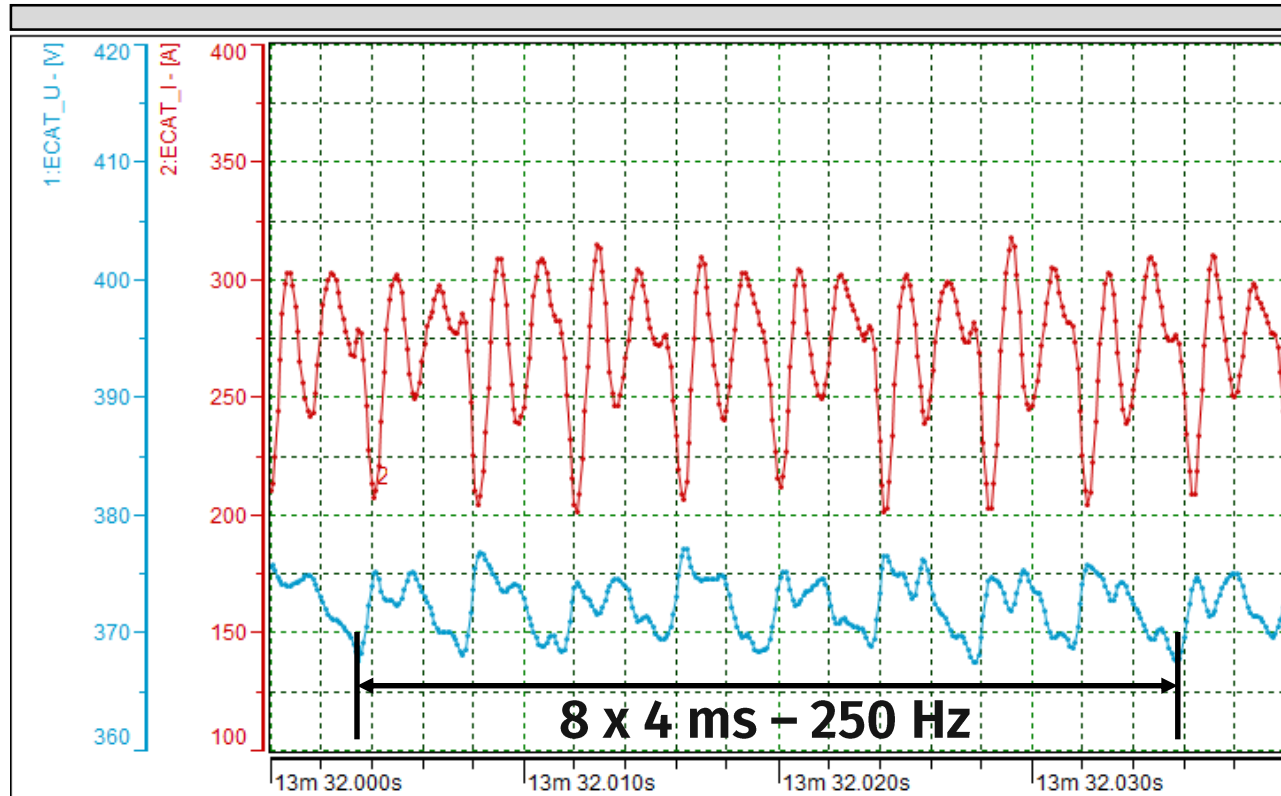
Current results from PWM-controlled voltage

Small consumers have built-in PWM control

Current is never only direct current

Current has alternating components

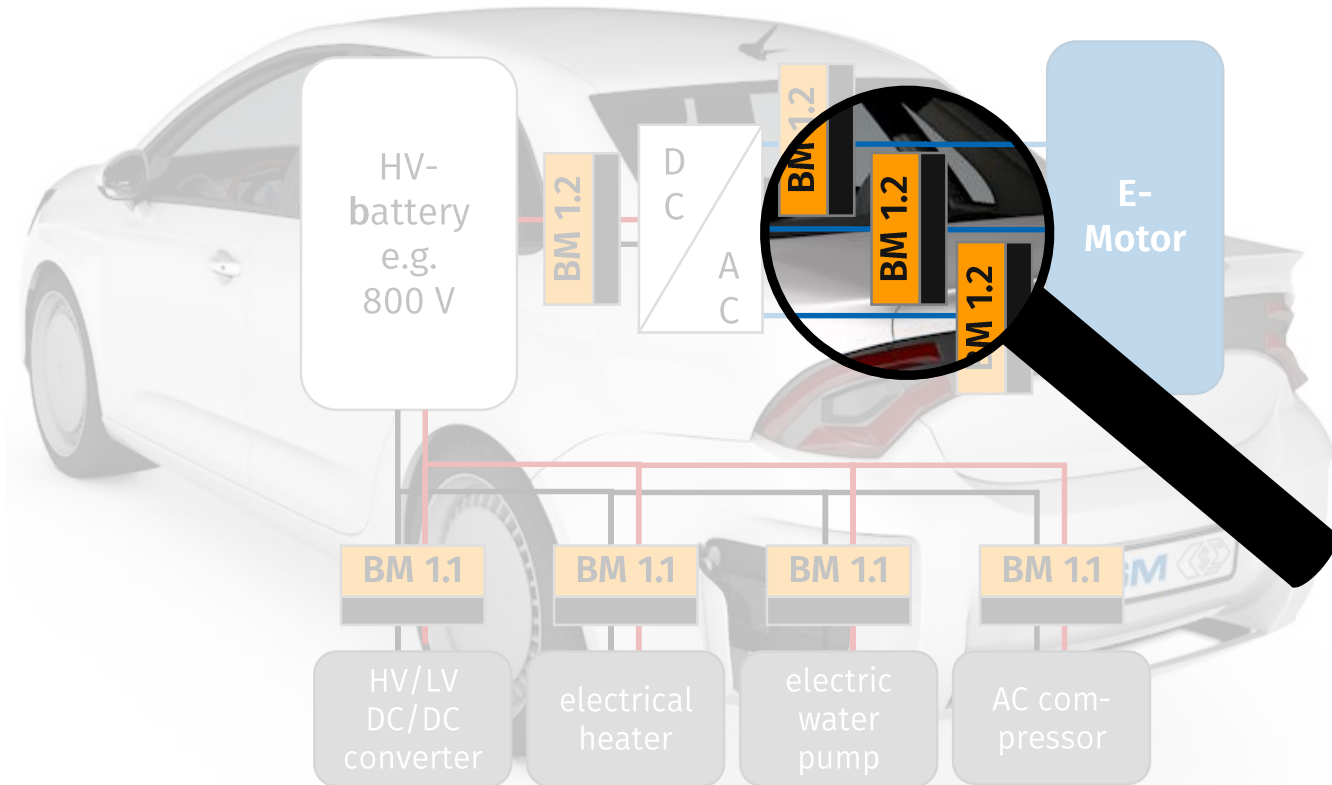
Battery to Inverter, HV BM 1.2, measurement of current and voltage



@ $P_{el} \sim 100 \text{ kW}$

- ▶ PWM controlled drive power
- ▶ Great dynamics of the current
- ▶ $I_{eff} = 271 \text{ A}$
- ▶ $I_{min} = 203 \text{ A}$
- ▶ $I_{max} = 312 \text{ A}$
- ▶ $\sigma_I = 27.6 \text{ A}$
- ▶ $U_{eff} = 372 \text{ V}$
- ▶ Requires measurement rate much faster than 250 Hz to capture mixed current signal

Electric current in electromobility



HV battery feeds consumer

- ▶ Inverter -> E-machine
- ▶ Small consumer

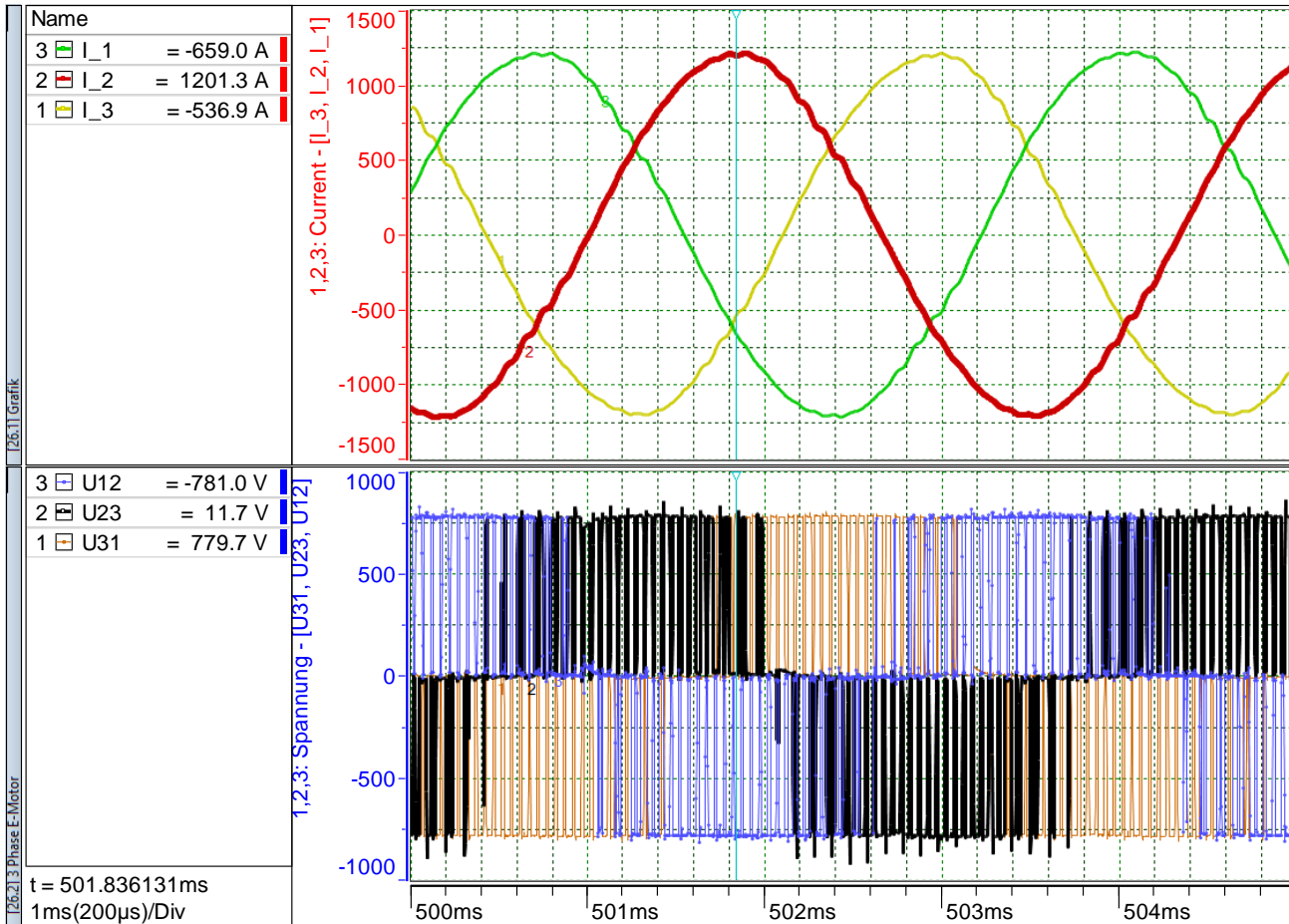
Current results from PWM-controlled voltage

Small consumers have built-in PWM control

Current is never only direct current

Current has alternating components

E-machine, three-phase, HV BM 1.2, measurement of current and voltage

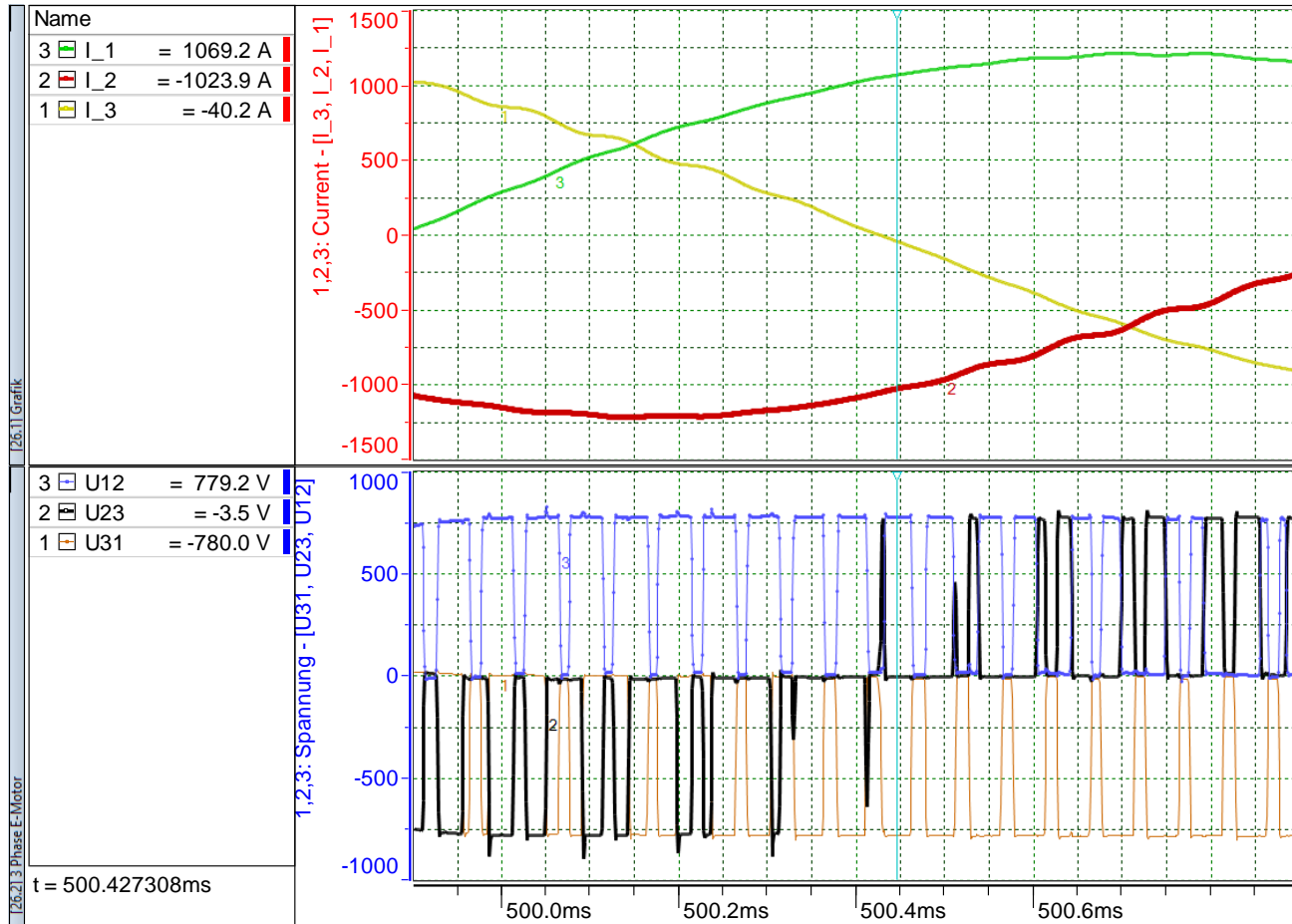


- ▶ Motor currents @ 300 Hz (3.3 ms)
- ▶ Synchronous machine
- ▶ 3 pole pairs
- ▶ 6000 rpm
- ▶ 1,200 A

- ▶ PWM and inverter visible

@ $P_{el} \sim 550 \text{ kW}$

E-machine, three-phase, HV BM 1.2, measurement of current and voltage



- ▶ PWM @ 20 kHz (50 μ s)
- ▶ U_{23} is inverted in the image

@ $P_{el} \sim 550$ kW

Current measurement in e-mobility with CSM measurement technology

- ▶ CSM offers several solutions for the proper application
 - Shunts, LEM, Hioki, Breakout Modules
 - ▶ Easy connection to and configuration with CSM Modules
 - Low Voltage (<60 V) and High Voltage (>60 V) Applications
- ▶ Robust, HV-safe, on-vehicle uses
- ▶ Test bench, road test

CSM **Xplained**
measurement technology

