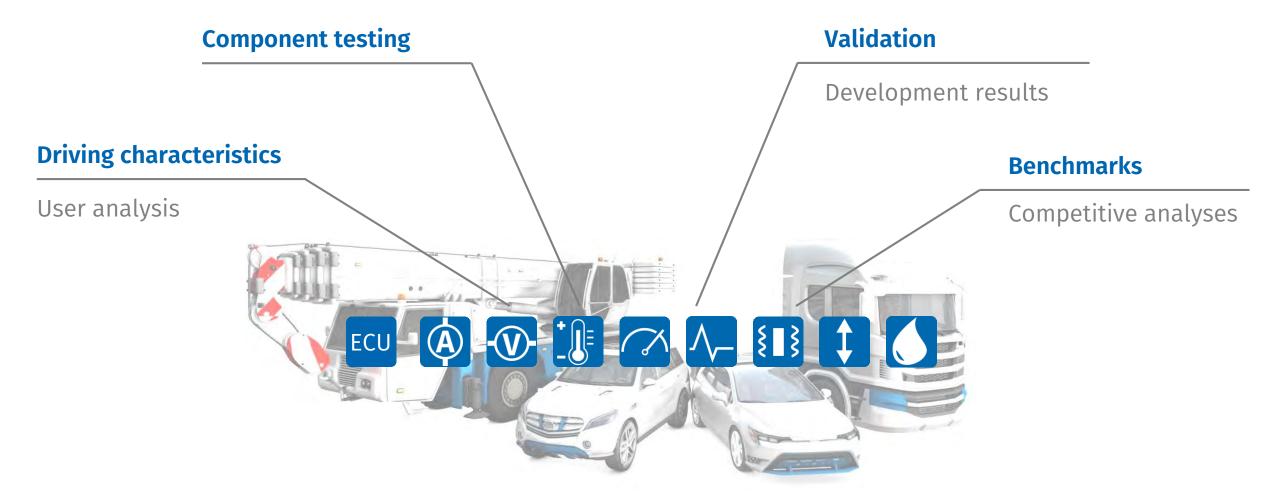


# Data logging of analog signals in worldwide fleet testing

**CSM Web Seminars** 

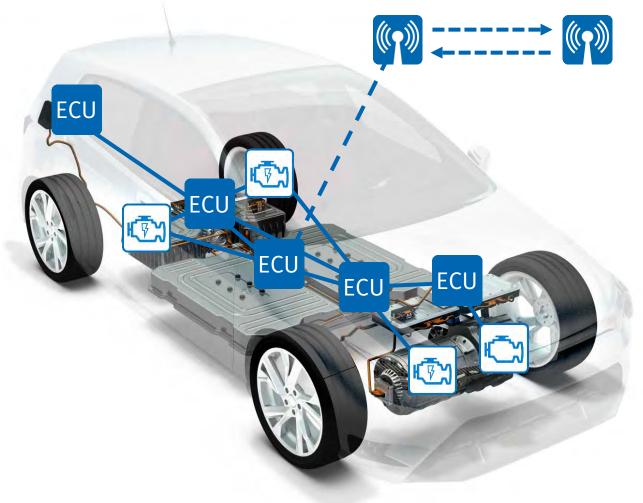


## **Data logging**





## **Electromobility as a complexity driver**



- Number of bus systems and signals increases
- Multiple engines (combustion and electric)
- Increasing digitalization
- Data exchange with external data sources
- **▶** Data volume in vehicles is increasing rapidly



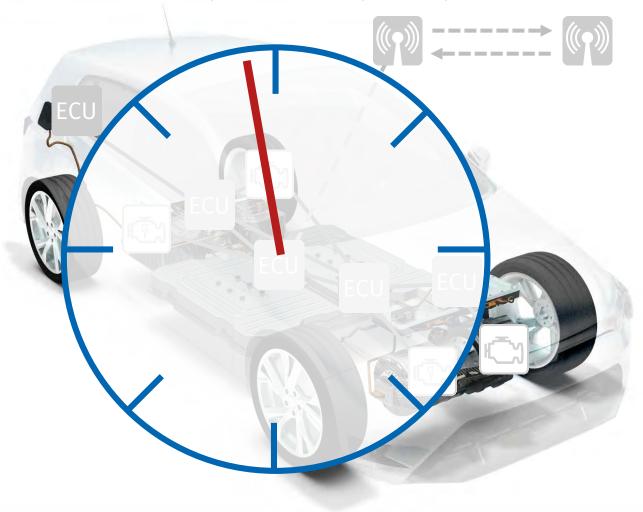
## **Electromobility as a complexity driver**



(Development engineer, German OEM)



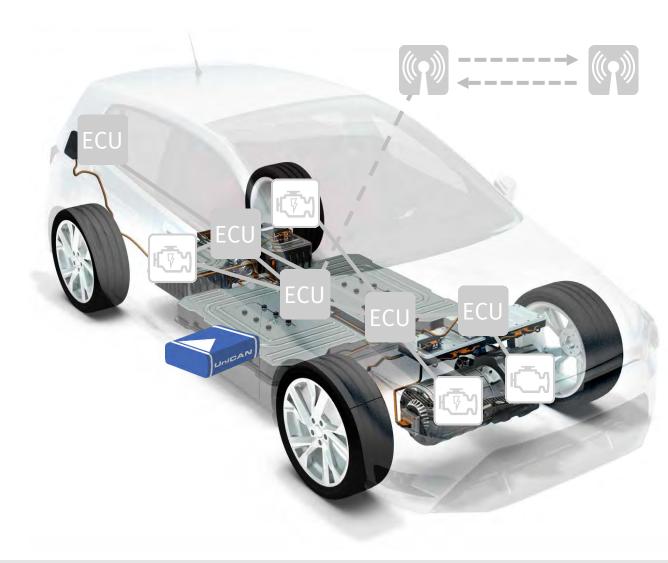
## **Electromobility as a complexity driver**



- Number of bus systems and signals increases
- Multiple engines (combustion and electric)
- Increasing digitalization
- Data exchange with external data sources
- Data volume in vehicles is increasing rapidly
- **▶** Less time for development

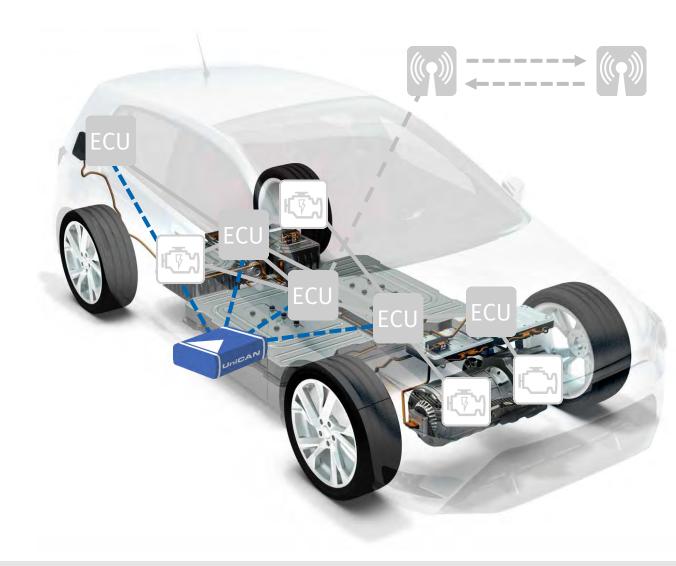


**▶** Autonomous operation



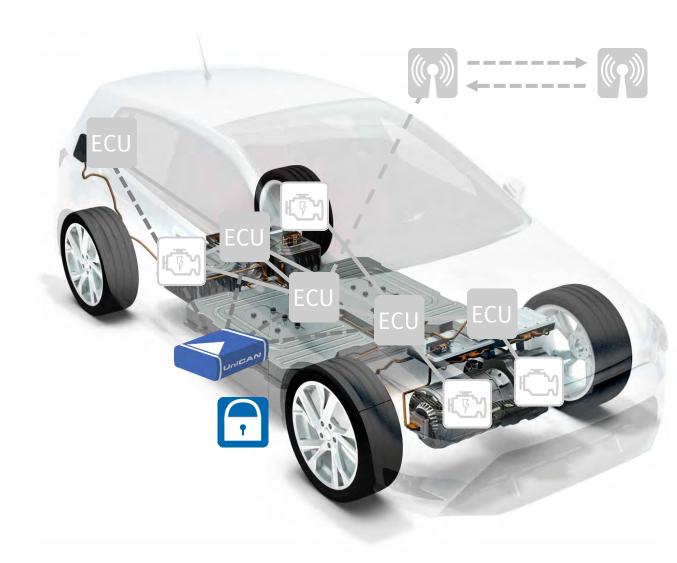


- ► Autonomous operation
- **▶** Efficient data acquisition



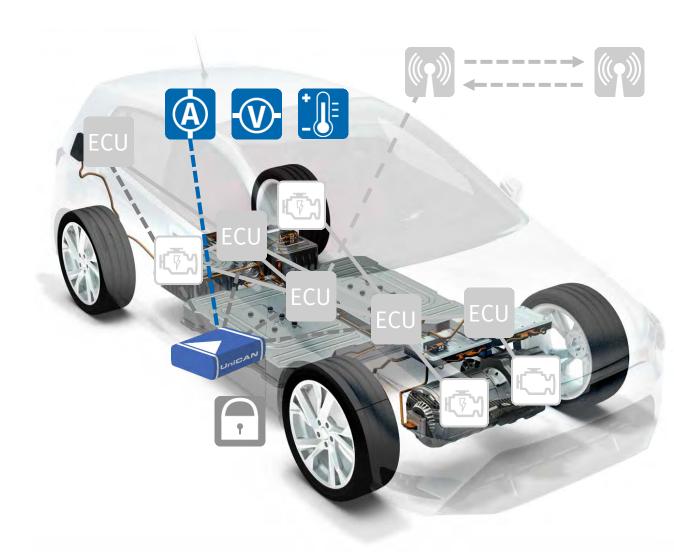


- ► Autonomous operation
- ► Efficient data acquisition
- **▶** Secure data storage



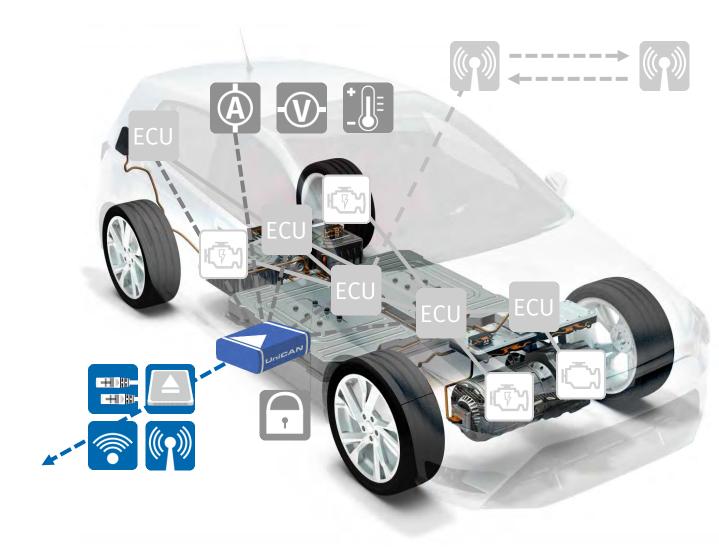


- ► Autonomous operation
- ► Efficient data acquisition
- ▶ Secure storage
- **▶** Integration of analog measurement data



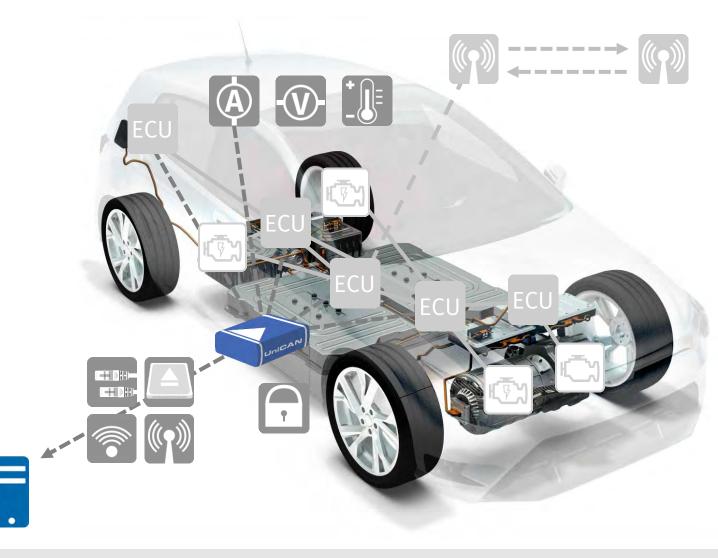


- ► Autonomous operation
- ► Efficient data acquisition
- ▶ Secure storage
- ► Integration of analog measurement data
- **▶** Flexible data transmission





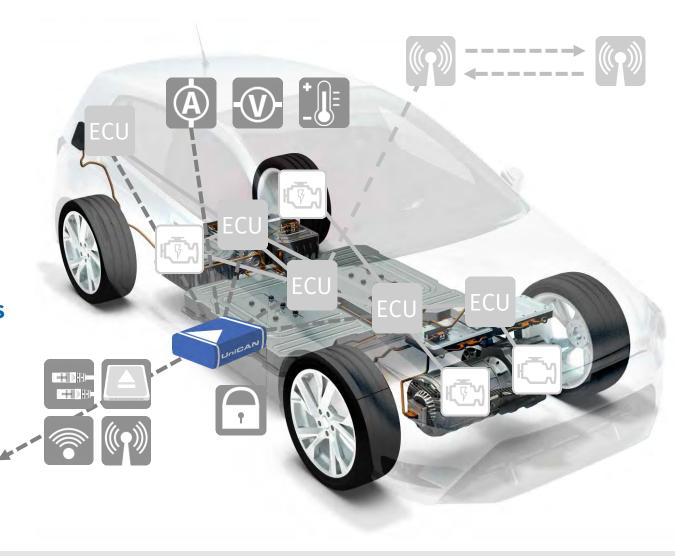
- ► Autonomous operation
- ► Efficient data acquisition
- ▶ Secure storage
- ► Integration of analog measurement data
- Flexible data transmission
- **▶** Trigger configuration





- ► Autonomous operation
- ► Efficient data acquisition
- Secure storage
- ► Integration of analog measurement data
- ► Flexible data transmission
- ► Trigger configuration
- ► Acquisition and management of large amounts

of data





Autonomous operation

Efficient data acquisition

Secure storage

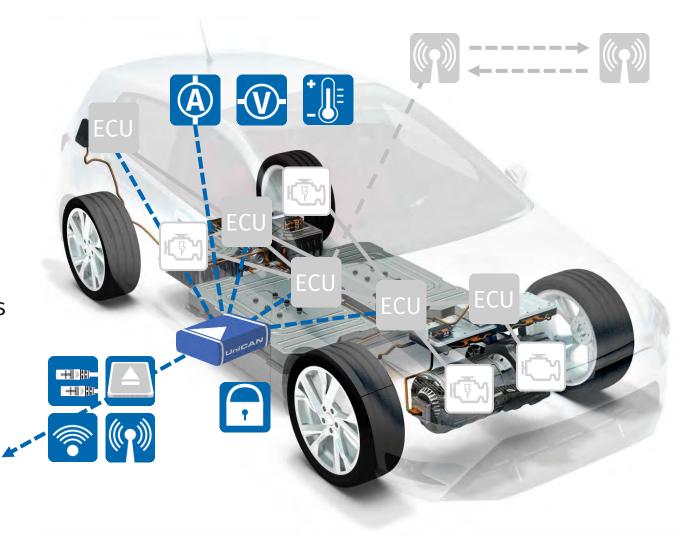
Integration of analog measurement data

► Flexible data transmission

► Trigger configuration

Acquisition and management of large amounts

of data





## **Test scenarios**







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### **Scenario 1**

Behavior of the engine control unit during mountain pass drives

#### **General conditions**

► Vehicle fleet: 20 cars

Duration: 2 weeks

#### **Challenges**

- Deadline pressure: Deadline for zero series approaching
- Problems with unresolved power fluctuations jeopardize project deadlines



Challenges



**▶** ECU data acquisition



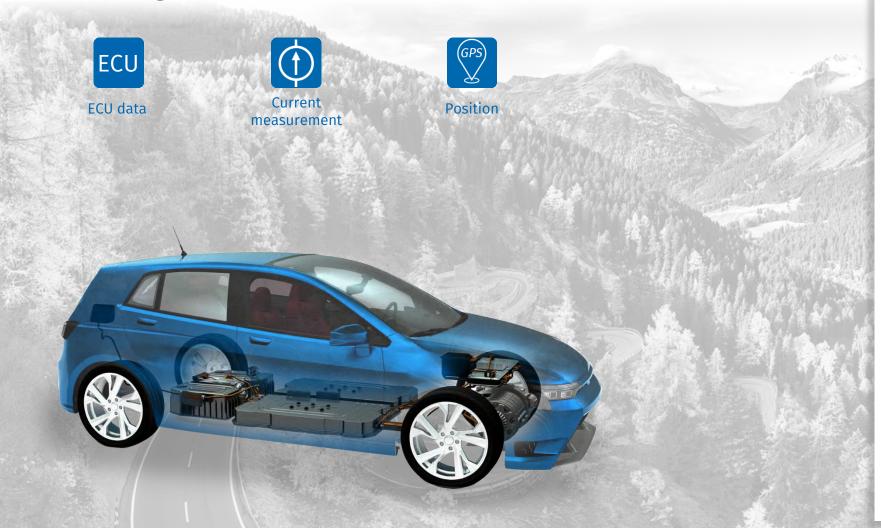
Challenges



- **▶** ECU data acquisition
- **▶** Additional current measurement
  - Verification ECU data



Challenges



- **▶** ECU data acquisition
- Additional current measurement
  - Verification ECU data
- **▶** Position data
  - Current fluctuations occur at full load (uphill driving)



Challenges

ECU

**ECU** data





transmission











- **▶** ECU data acquisition
- Additional current measurement
  - Verification ECU data
- **Position data** 
  - Current fluctuations occur at full load (uphill driving)
- **▶** Transmission of measurement data while driving
  - Fast analysis of the data



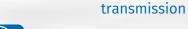
Challenges

ECU

**ECU** data











Remote configuration





**Position data** 

**►** ECU data acquisition

load (uphill driving)

Verification ECU data

**▶** Transmission of measurement data while driving

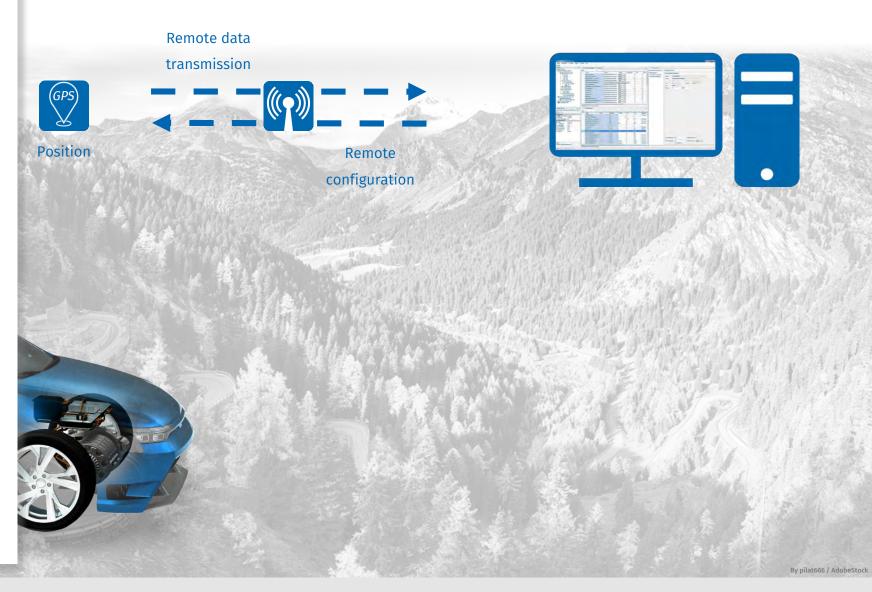
Additional current measurement

- Fast analysis of the data
- Modification of the logger configuration



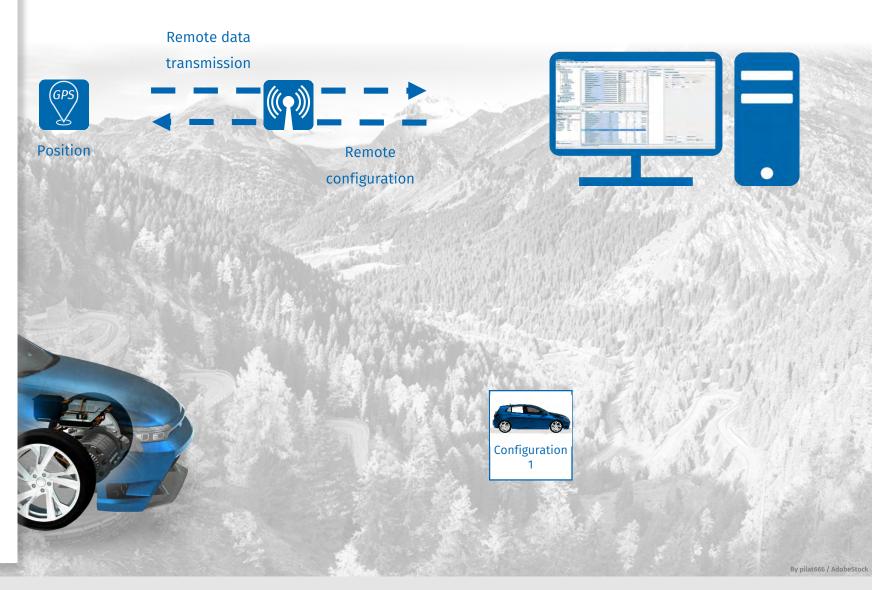


- **►** ECU data acquisition
- ► Additional current measurement
  - Verification ECU data
- **▶** Position data
  - Current fluctuations occur at full load (uphill driving)
- ➤ Transmission of measurement data while driving
  - Fast analysis of the data
  - Modification of the logger configuration
- ► Simple data management
  - Time factor



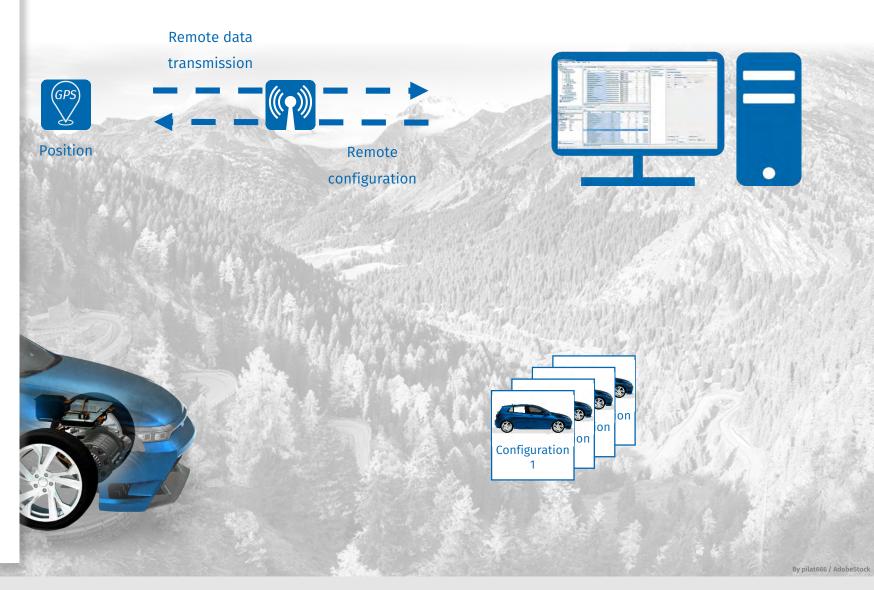


- **►** ECU data acquisition
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  - Verification ECU data
- **▶** Position data
  - Current fluctuations occur at full load (uphill driving)
- ➤ Transmission of measurement data while driving
  - Fast analysis of the data
  - Modification of the logger configuration
- **▶** Simple data management
  - Time factor



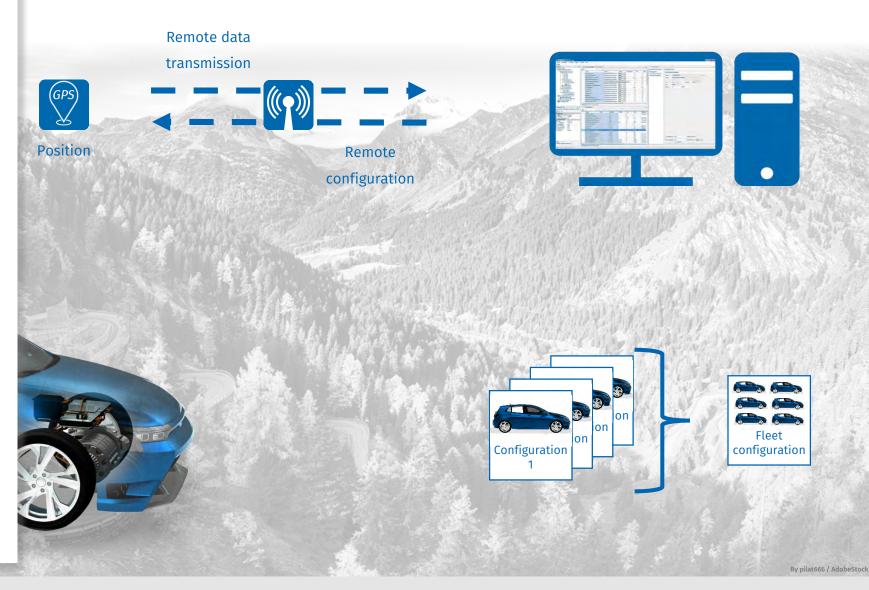


- **►** ECU data acquisition
- ► Additional current measurement
  - Verification ECU data
- **▶** Position data
  - Current fluctuations occur at full load (uphill driving)
- ► Transmission of measurement data while driving
  - Fast analysis of the data
  - Modification of the logger configuration
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  - Time factor





- **►** ECU data acquisition
- ► Additional current measurement
  - Verification ECU data
- **▶** Position data
  - Current fluctuations occur at full load (uphill driving)
- ► Transmission of measurement data while driving
  - Fast analysis of the data
  - Modification of the logger configuration
- **▶** Simple data management
  - Time factor
- Fleet management / measurement configuration in one project





Challenges Remote data transmission ECU Current Position **ECU** data Remote measurement configuration Fleet Configuration configuration By pilat666 / AdobeStock

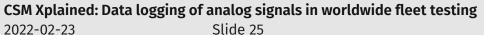


Hardware setup

Remote data

► ECU data acquisition







Hardware setup



## **Data logger UniCAN 3 ETH**

UniCAN 3 ETH on www.csm.de

### Data logger for mobile applications with Ethernet interface

- Ethernet interface
- 9 CAN interfaces
- Support AUTOSAR PDU
- Numerous options (CANsend, CAN stimulation, Wake-on-CAN) for application-specific configuration
- Recording on CF card (up to 64 GB)



UniCAN 3 ETH backside

By pilat666 / AdobeS

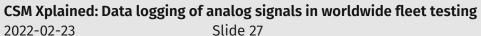


Hardware setup

Remote data

► ECU data acquisition







Hardware setup



### **Protocols**

#### **Ethernet interface**

- Recording of Ethernet frames (UDP or TCP)
- Support of XCP-on-Ethernet

#### **CAN** interfaces

- ► CCP, XCP-on-CAN, CCP Block Read, OBD2 / EOBD, J1939
- CAN FD
- Impact free operation ensured (read-only mode)

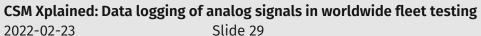


Hardware setup

Remote data









Hardware setup



### Integration of measurement data from measurement modules



Frequencies



LEM sensor package



Analog signals



ECAT AD4 IG100



CAN

Analog signals (HV safe)

**EtherCAT®** 



XCP-Gateway

XCP-on-

Ethernet

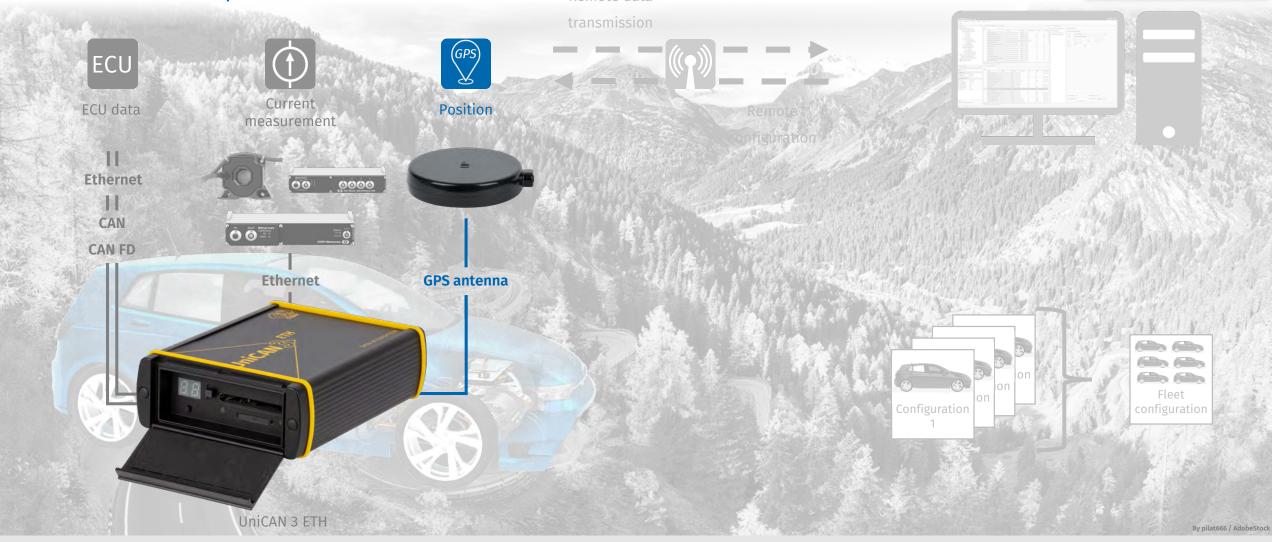
UniCAN 3 ETH backside



Hardware setup

Remote data

Position data







Hardware setup

Remote data

▶ Remote data transmission

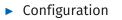


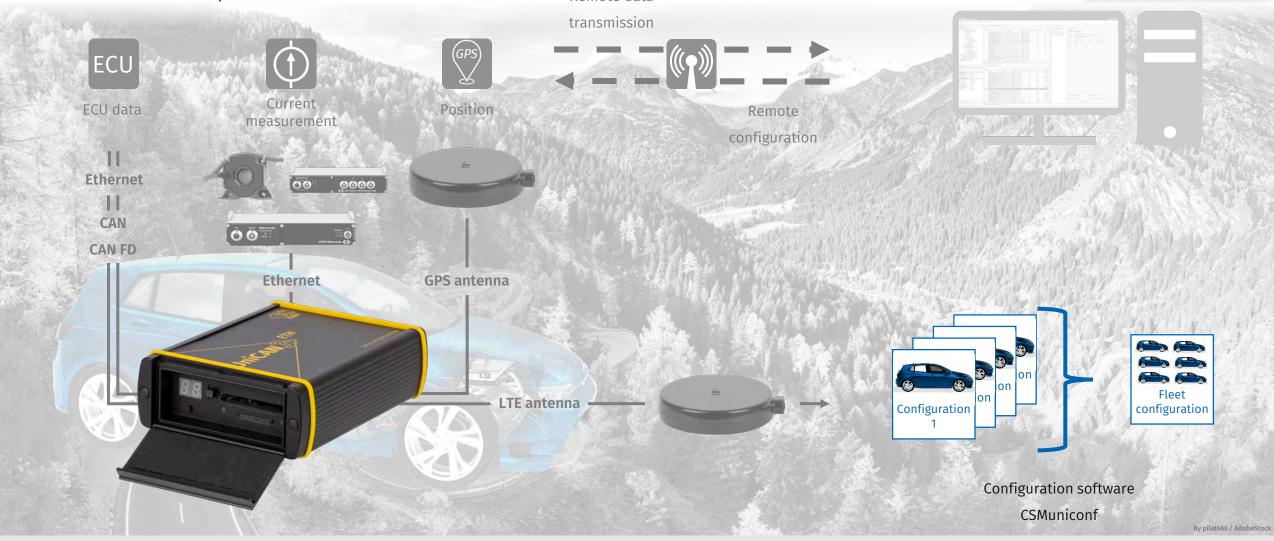


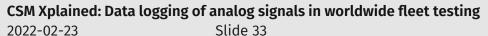
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Software setup

Remote data



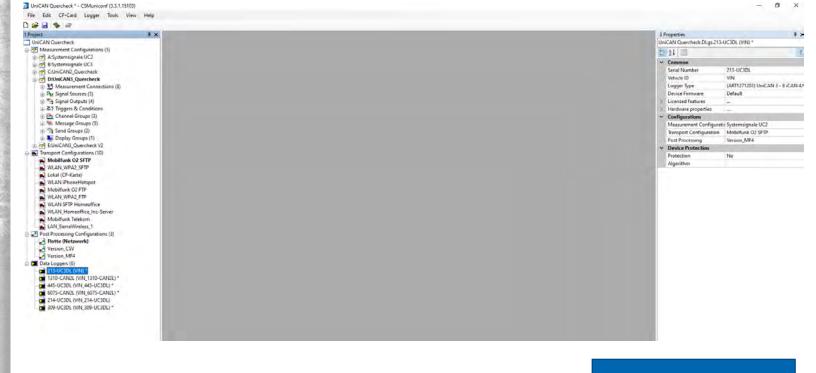




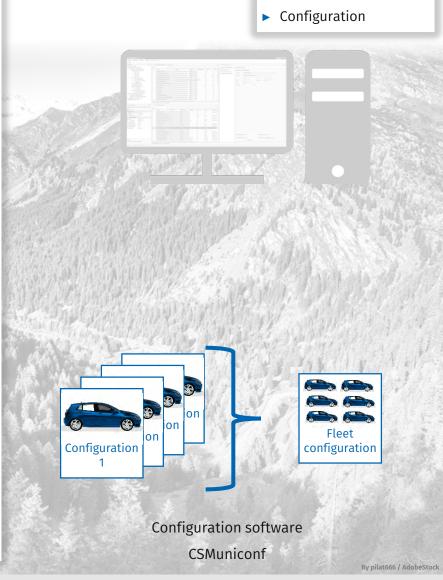
(I) CSM



#### Configuration software for UniCAN data logger



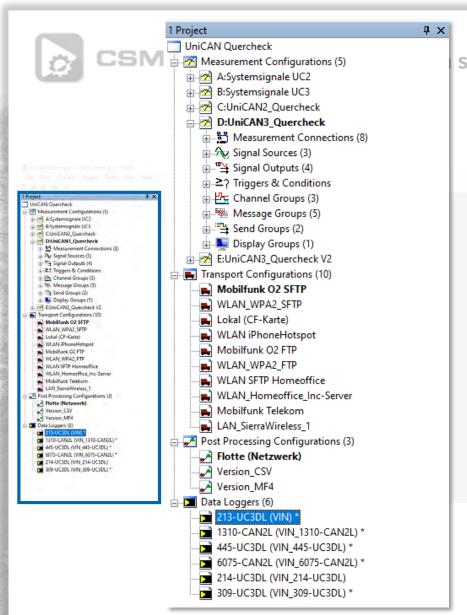
CSMuniconf on www.csm.de





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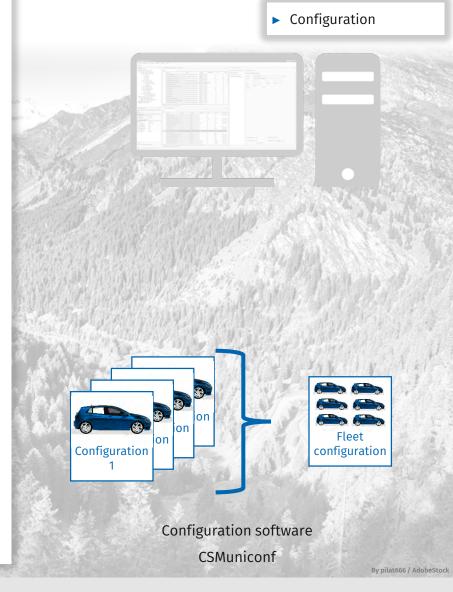




software for UniCAN data logger

#### **Fleet management**

Management and configuration of all loggers in one project file



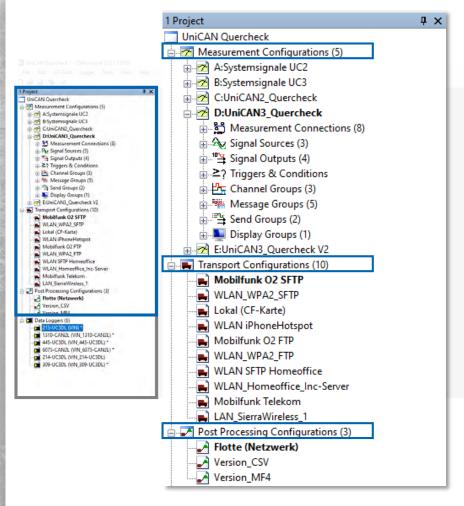
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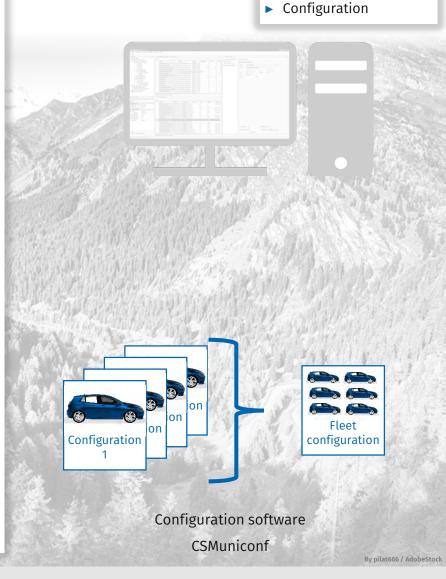


#### Configuration software for UniCAN data logger



#### **Fleet management**

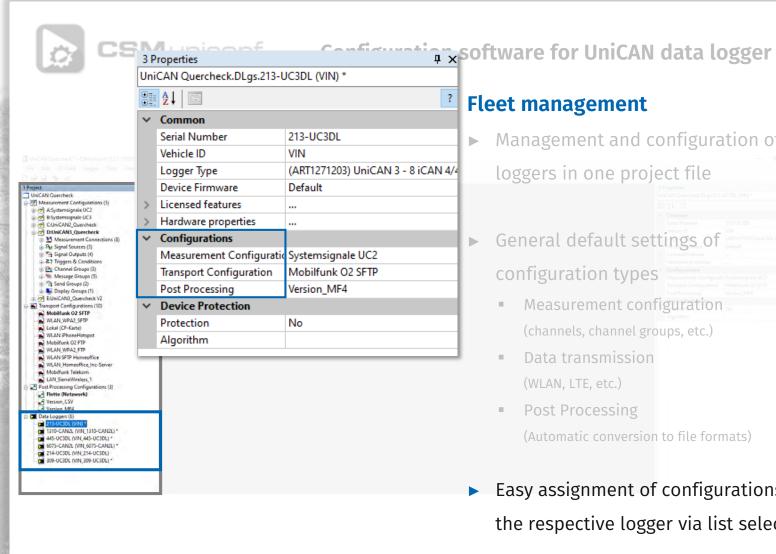
- Management and configuration of all loggers in one project file
- General default settings of configuration types
  - Measurement configuration (channels, channel groups, etc.)
  - Data transmission (WLAN, LTE, etc.)
  - Post Processing (Automatic conversion to file formats)





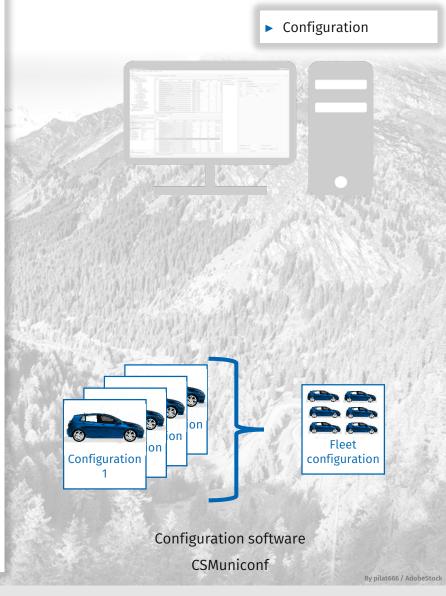
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#### **Fleet management**

- Management and configuration of all loggers in one project file
- General default settings of configuration types
- Measurement configuration (channels, channel groups, etc.)
- Data transmission (WLAN, LTE, etc.)
- Post Processing (Automatic conversion to file formats)
- Easy assignment of configurations to the respective logger via list selection



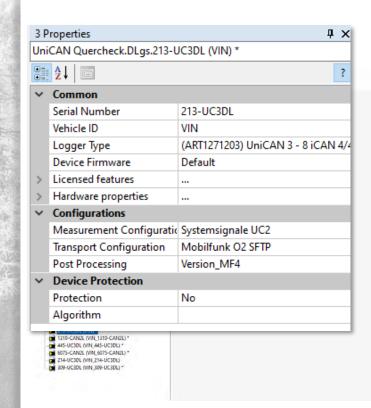


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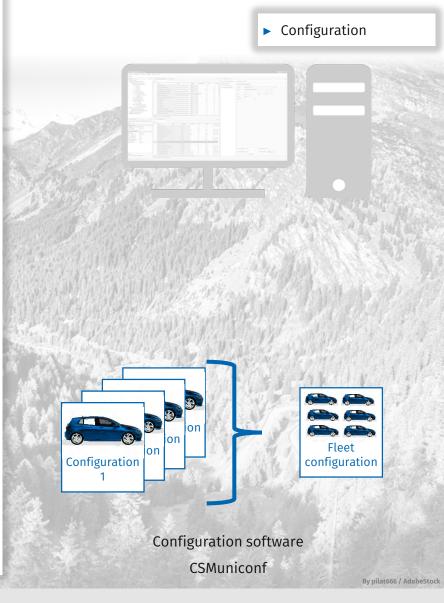


#### Configuration software for UniCAN data logger



#### **Remote (Re-) Configuration**

- Configuration update
- Firmware update
- Option update
- ► Target server update
- Additional transmission of status information such as
  - Memory card fill level
  - GPS signal strength
  - Bus loads
  - Etc...





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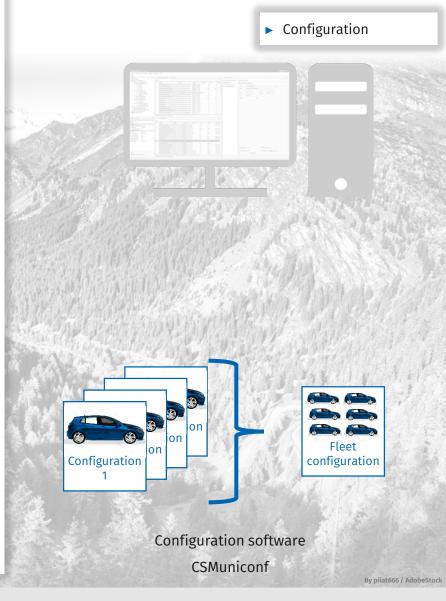


#### **Configuration software for UniCAN data logger**

#### **Trigger**

- Automatic recording of defined events
- Short snapshot recording with pre-trigger and high resolution
  - Current peaks at full load
  - Geofencing: data recording only in the target area

**Efficient data recording to save storage space** 



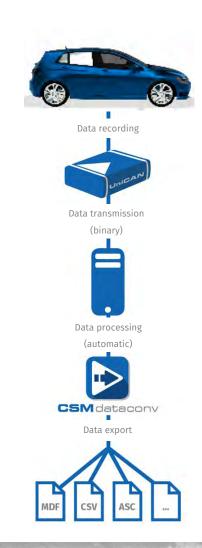


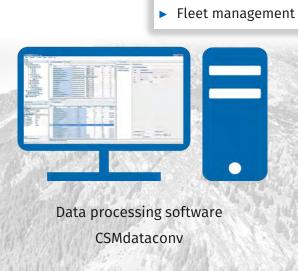


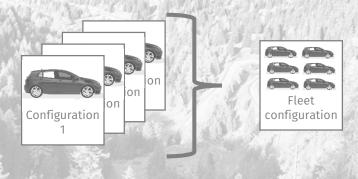
#### Server-based data processing

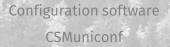
- Automatic further processing and conversion of recorded measurement data
- Conversion into desired data format
  - MDF
  - CSV
  - ASC
- Automatic sorting and data segmentering (e.g. one file per day, per hour, per test run...)











By pilat666 / AdobeStock



### A trip to the Alps



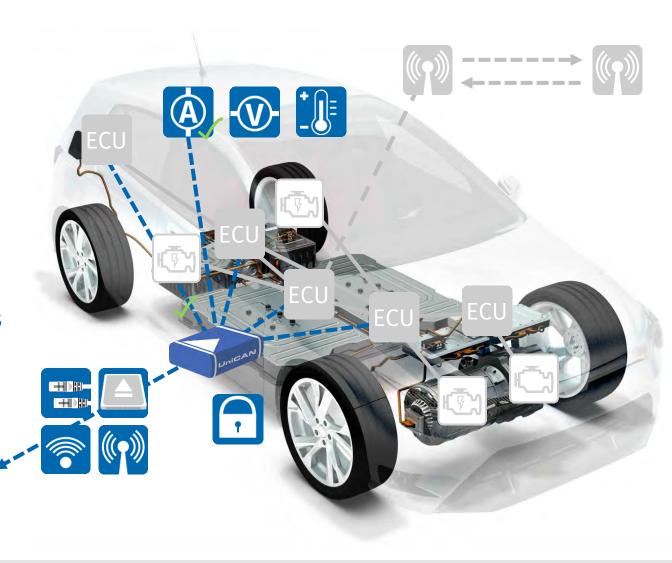


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### **Data logger requirements**

- ► Autonomous operation
- ✓ ► Efficient data acquisition
  - Secure storage
- ✓ ► Integration of analog measurement data
  - ► Flexible data transmission
- ✓ ► Trigger configuration
- ✓ ► Acquisition and management of large amounts of data





### **City tour**



### **Scenario 2**

**Driving characteristics of the end customer during urban driving** 

#### **General conditions**

▶ Vehicle fleet: 40 cars

Duration: 9 months

#### **Challenges**

► High temperatures

www.csm.de

Drivers are end customers (not professional test drivers)

By Andrea Izzotti / Adobes



**▶** High ambient temperatures

by Allurea izzotti / Auobesti



- **▶** High ambient temperatures
- **▶** Hidden installation in the vehicle
  - No distraction of the driver
  - No self-heating (passive cooling)

y Andrea Izzotti / AdobeSto





- **▶** High ambient temperatures
- **▶** Hidden installation in the vehicle
  - No distraction of the driver
  - No self-heating (passive cooling)
- **▶** ECU data acquisition

y Andrea Izzotti / AdobeSto





- **▶** High ambient temperatures
- **▶** Hidden installation in the vehicle
  - No distraction of the driver
  - No self-heating (passive cooling)
- **►** ECU data acquisition
- **▶** Position data

y Andrea Izzotti / AdobeSto







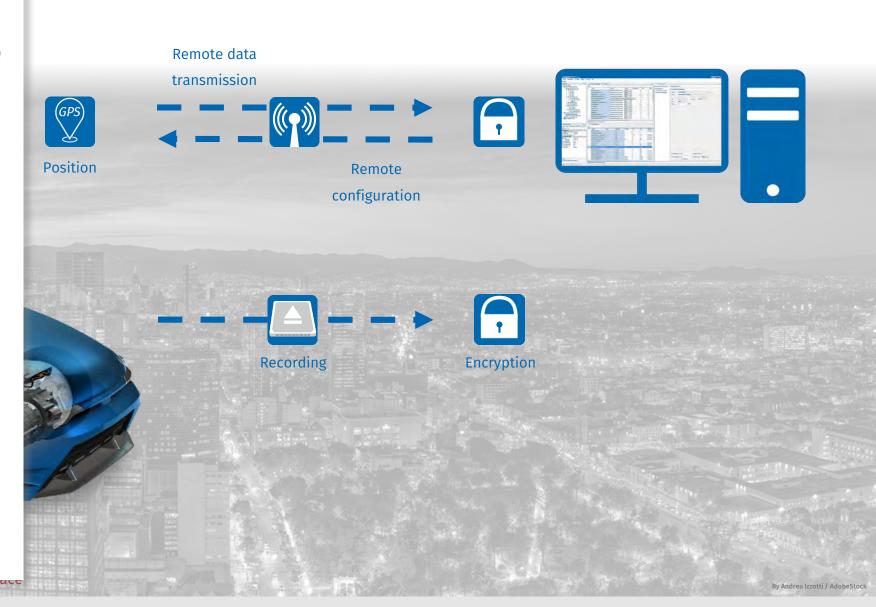
- **▶** High ambient temperatures
- ► Hidden installation in the vehicle
  - No distraction of the driver
  - No self-heating (passive cooling)
- **►** ECU data acquisition
- **Position data**
- Remote access



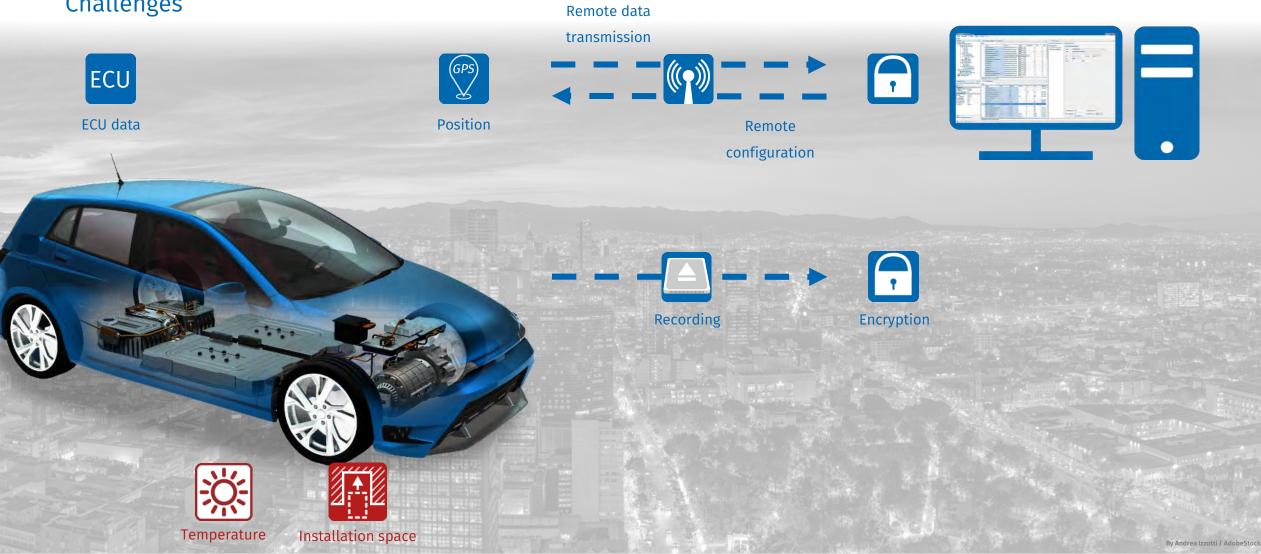


Remote data

- **▶** High ambient temperatures
- ► Hidden installation in the vehicle
  - No distraction of the driver
  - No self-heating (passive cooling)
- **►** ECU data acquisition
- **▶** Position data
- **▶** Remote access
- Secure storage and transmission of data













### **City tour** Hardware setup



### **Data logger UniCAN 3**

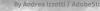
#### **Data logger for mobile applications**

- ► 12 CAN interfaces
- Operating temperature range: -40 °C to +80 °C
- ▶ Dimensions (W × H × D): 109 × 45 × 158 mm
- Support of AUTOSAR PDU
- Numerous options for application-specific configuration
- Recording on CF card (up to 64 GB)

UniCAN 3 on www.csm.de



UniCAN 3 backside

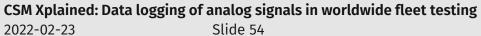














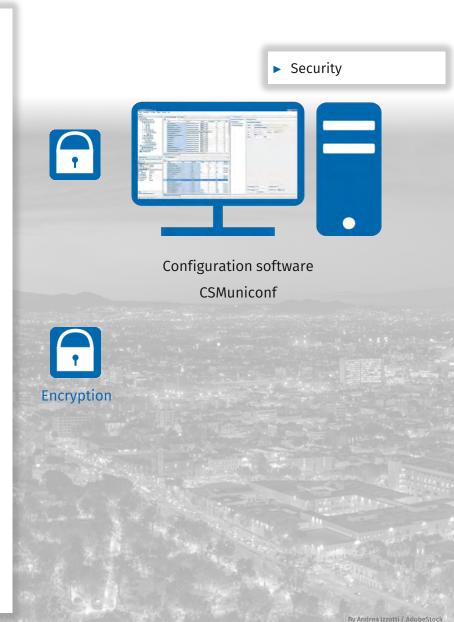






#### **Security**

- ▶ No configuration files (dbc, a2l) are stored directly on CF card!
  - Instead: Binary configuration file
- Measurement data also stored in a binary file format on CF card
- Data transfer to SFTP server





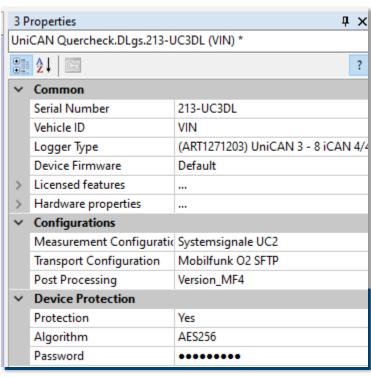
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#### **Security**

- ▶ No configuration files stored direct
  - Binary configuration file
- ▶ Measurement data also stored in a
- ▶ Data transfer to SFTP server
- Additional encryption (Device Protection)
  - Algorithm with 3 levels
  - Password protected







By Andrea Izzotti / AdobeStock

### **City tour** Overview

- ► High ambient temperatures
- ► Hidden installation in the vehicle
- ► ECU data acquisition
- ▶ Position data
- ▶ Remote access
- Secure storage and transmission of data



Remote data transmission





configuration



Configuration software **CSMuniconf** 

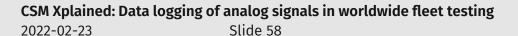


Recording

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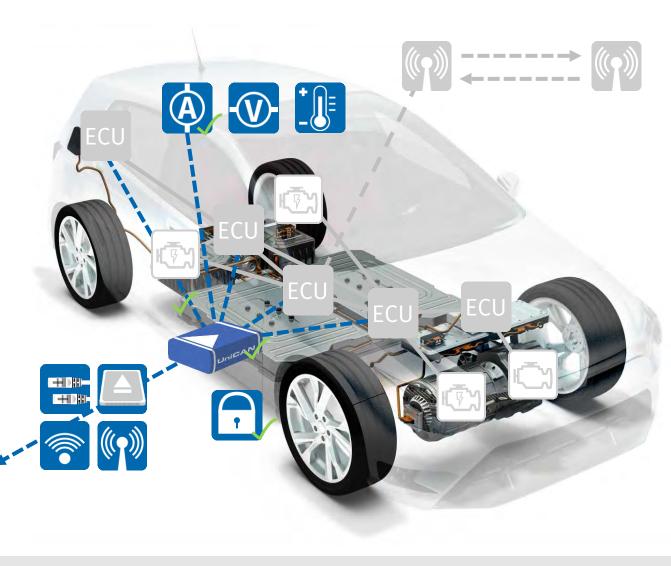
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### **Data logger requirements**

- ✓ ► Autonomous operation
- Efficient data acquisition
- ✓ ► Secure storage
- ✓ ► Integration of analog measurement data
  - ► Flexible data transmission
- ✓ ► Trigger configuration
- ✓ ► Acquisition and management of large amounts









### **Scenario 3**

#### Behavior of the engine control unit in extremely cold conditions

#### **General conditions**

► Vehicle fleet: 10 trucks

Duration: 6 weeks

#### **Challenges**

- Extremely low temperatures (down to -40 °C)
- Poor mobile network coverage



Challenges



Extremely low ambient temperatures

By yanikap / AdobeSt



Challenges



- Extremely low ambient temperatures
- **▶** Low power consumption
  - Low load on vehicle battery

By yanikap / AdobeSt



Challenges



- Extremely low ambient temperatures
- **▶** Low power consumption
  - Low load on vehicle battery
- **►** ECU data acquisition

By yanikap / AdobeSto



Challenges



- Extremely low ambient temperatures
- **▶** Low power consumption
  - Low load on vehicle battery
- **►** ECU data acquisition
- ► Parallel recording of temperature measurement data

By vanikap / AdobeS



Challenges



- Extremely low ambient temperatures
- **▶** Low power consumption
  - Low load on vehicle battery
- **►** ECU data acquisition
- Parallel recording of temperature measurement data
- ▶ Delay-free recording of the start behavior

By vanikap / AdobeS



Challenges

**Temperature** 







Remote





- Extremely low ambient temperatures
- **▶** Low power consumption
  - Low load on vehicle battery
- ► ECU data acquisition
- ▶ Parallel recording of temperature measurement data
- Delay-free recording of the start behavior
- **▶** Option for radio dead zones





Power consumption

Challenges





Temperatures



Remote data



Remote configuration











Power consumption

By yanikap / AdobeStock



Hardware setup

**ECU** 

Remote data



configuration















Power consumption





By yanikap / AdobeStock

Ambient temperatures

UniCAN 3 ETH

Hardware setup



### **Datea logger UniCAN 3 ETH**

#### Data logger for mobile applications with Ethernet interface

- ▶ Operating temperature range: -40 °C to +80 °C
- Power consumption
  - Normal operation: 3.6 W
  - Full load: 7.3 W



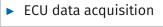
UniCAN 3 ETH

Divingilian / AdabaCa



Hardware setup

Remote data





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Hardware setup

Remote data

Temperature measurement





Software setup

Delay-free recording





By yanikap / AdobeStock

Power consumption

Temperature



#### **Delay-free recording**

- ► FPGA architecture
  - no operating system necessary
  - cold start <1 second</li>
  - low power consumption <1 mA,</li>
     in sleep mode
- Wake-on-CAN
  - Automatic start due to bus activity
  - No Message Lost

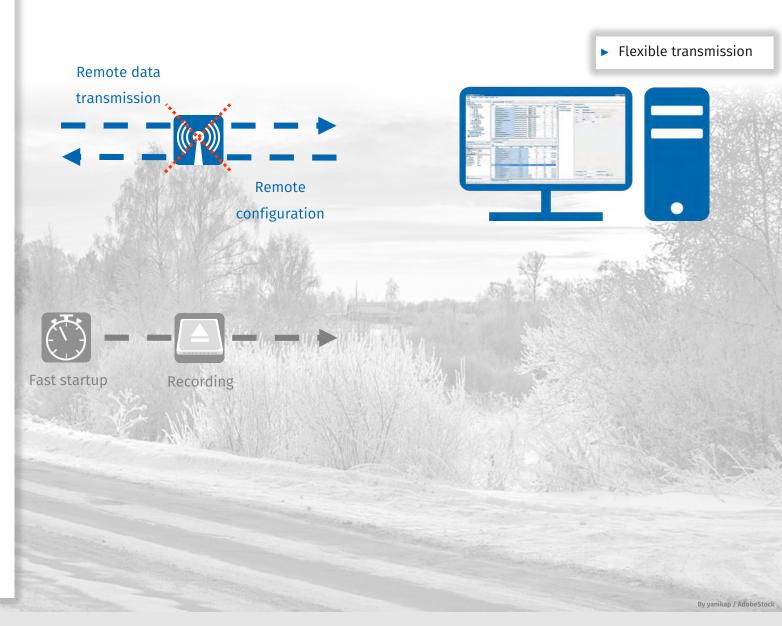






#### **Handling of Radio Dead Zones**

- Additional setting of fixed transmission time
- Data transmission only from selected measurement channels (minimizes data volume)
- Logging of same channels with different sampling rates to transmit channels with reduced data volume





Overview







Remote data

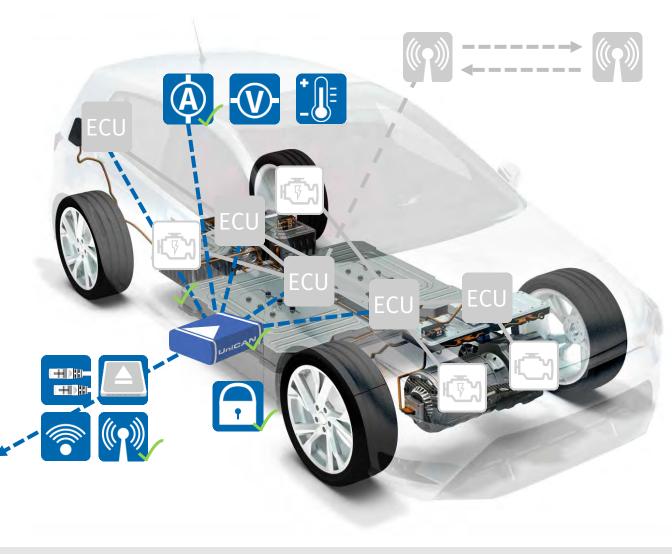
- Extremely low ambient temperatures
- ► Low power consumption
- ► ECU data acquisition
- Recording of temperature measurement data
- ▶ Delay-free recording
- ▶ Option for radio dead zones

By yanikap / AdobeStock



### **Data logger requirements**

- ✓ ► Autonomous operation
- ✓ ► Efficient data acquisition
- ✓ ► Secure storage
- ✓ ► Integration of analog measurement data
- ✓ ► Flexible data transmission
- ✓ ► Trigger configuration
- ✓ ► Acquisition and management of large amounts of data





### **Vector and CSM data logger portfolio**

#### **CSM UniCAN 3 data loggers**







Acquisition of analog and digital measurement values, internal ECU parameters and vehicle bus communication.

**Easy configuration** 



#### **Vector VP smart logger**



Vector Logger Suite (VLS)

CANape log (eMobilityAnalyzer)

vMDM

Intelligent high performance logging solution for emobility and ADAS developments.

In-depth real time calculations and analyses.



2022-02-23

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### Data logging of analog signals in worldwide fleet testing





### **E-Mobility Measurement System**







Hardware and software packages with flexible customization options for many test environments and requirements





#### **About CSM**

CSM has been setting technological standards for decentralized measurement technology in vehicle development for over 35 years. Our CAN bus and EtherCAT® measurement devices support worldwide renowned vehicle manufacturers, suppliers and service providers in their developments.

Continuous innovation and long-term satisfied customers are our guarantee for success. Together with our partner Vector Informatik, we have developed an easily scalable and powerful E-Mobility

Measurement System for hybrid and electric vehicles and are constantly expanding the areas of application. With our high-voltage safe measurement systems designed for fast and synchronous measurements and power analyses, we actively accompany the change to E-Mobility.

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