

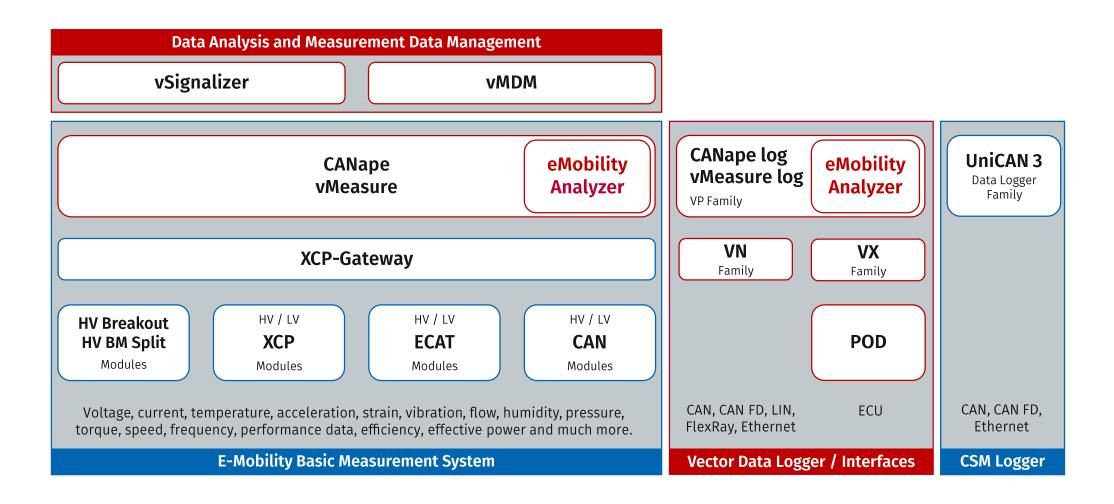
MÜNCHEN DÜSSELDORF WOLFSBURG

# Leistungsmessung mit CSM Messmodulen und dem Vector eMobilityAnalyzer





### Vector CSM E-Mobility Measurement System





VECTOR

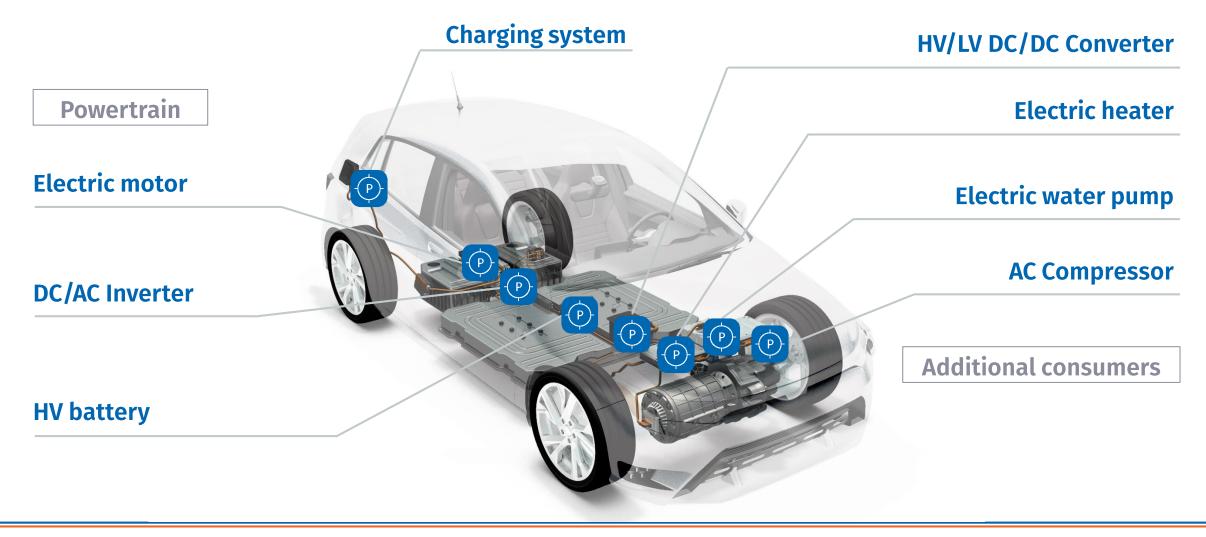
Vector CSM TechDay - Leistungsmessung mit CSM Messmodulen und dem Vector eMobilityAnalyzer

### **Basics Electrical Power**

Electrical power	$P = U \times I$	Direct current (DC)
Instantaneous power	$p(t) = u(t) \times i(t)$	
Active power	$P = \frac{1}{T} \int_0^T u(t) \times i(t) dt$	
Active power	$P = \frac{1}{N} \sum_{n=0}^{N} u_n i_n \Delta t$	
Active power	$P = U_{rms} \times I_{rms} \times \lambda$	Alternating current (AC)
Apparent power	$S = U_{rms} \times I_{rms}$	Total apparent power
Power factor	$\lambda = \frac{ P }{S}$	Any curve shape
<b>Power factor</b> = Displacement factor	$\cos\varphi = \frac{ P }{S}$	Sinusoidal signal
Reactive power	$Q = \sqrt{S^2 - P^2}$	Total reactive power

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### **Power measurements**





### **CSM's HV-safe Voltage measurements** Examples

### HV AD4 XW1000

- ► To measure up to 4x U
- up to ±1000 V,
  ±2000 V for spike
- ECAT up to 1 MS/s

### HV AD4 XW4000

- ► To measure up to 4x U
- up to ±1000 V,
  ±2000 V for spikes
- XCPoE up to 4 MS/s





### CSM's Current Clamp

### **CSM Current Clamp**

- To measure one current
- ▶ ±20 A .. ±1000 A
  - Analogue output ±2 V
  - DC-supply 10 V .. 30 V

### AD4 IG1000

► To measure 1.. 4 voltages



### **CSM's LEM Sensor Package**

### **LEM Sensor Package**

- ► To measure one current
- ▶ ±5 A .. ±1250 A
  - Analogue output ±5 V
  - DC-supply 9 V .. 36 V
- Loop is potted



### AD4 IG1000

► To measure 1.. 4 voltages



### **CSM HV Measurement Modules - active Breakout Modules**

### HV Breakout Modules (BM) for in vehicle testing and dynamometer measurements

- Safe measurement of voltages up to ±2 kV
- Safe measurement of currents up to ±2 kA
- CAN and ECAT output, up to 1 MHz
- Comprising 1 or 3 shunts







### CSM HV Breakout Modules to Measure I and V and to Calculate P

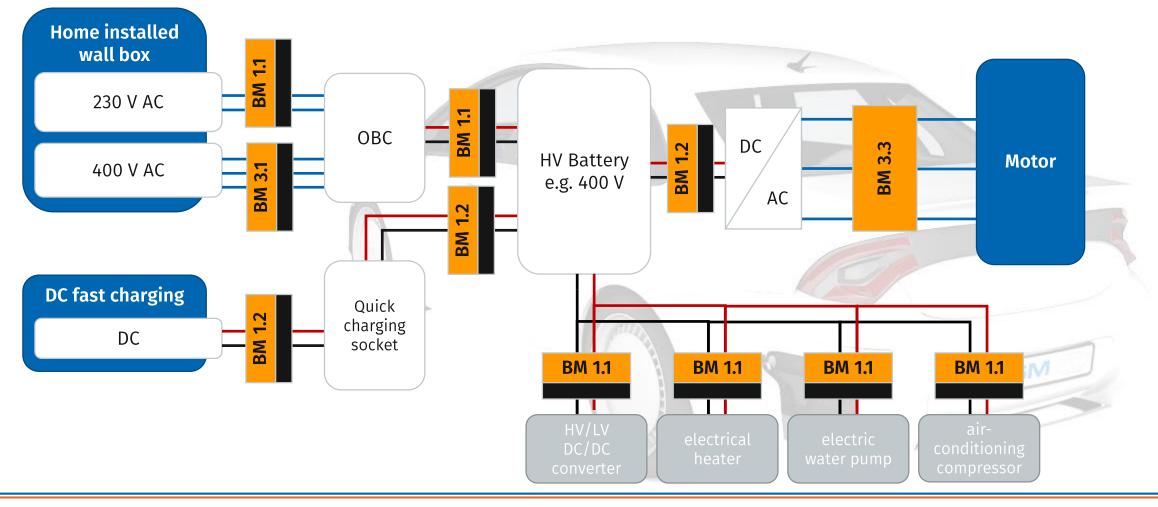
Various breakout modules available

- Single phase measurements of
  - V up to 1 kV working voltage and 2 kV of spikes
  - Inserts, I<sub>nom</sub>: ±1000 A, ±500 A, ±250 A, ±125 A
  - I<sub>spike</sub> with shunts up to ±2000 A
- EtherCAT output up to 1 MHz per channel
- Optional CAN output for data loggers
- Calculation of RMS-values and power





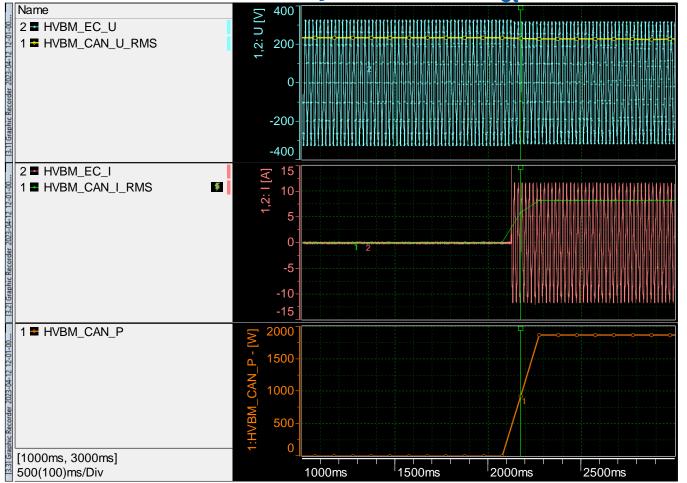
### Power Measurements in HV Electrical Systems with HV BM's (Breakout Modules)





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# DUT: Electric kettle, 1 phase, U, I, P<sub>el</sub>



### HV BM 1.2 with option Calc.

- ► To measure U, I
- To calculate P, U\_rms, I\_rms
- To save CPU load on PC
- ► To save SSD on PC

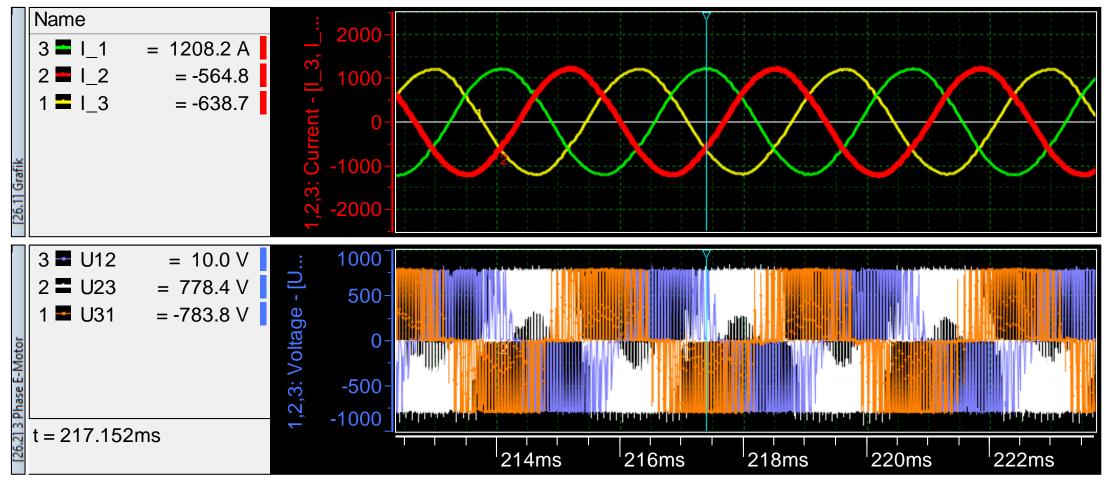


# DUT: Electric Motor, 3 phases, U, I, P, ...

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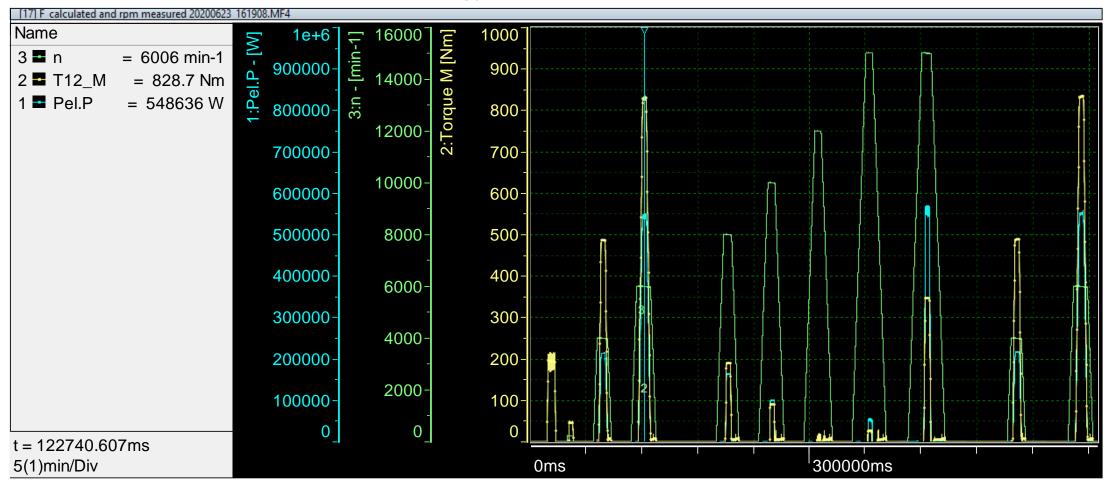
### DUT: Electric Motor, 3 phases, U, I, I\_rms up to 860 A



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# DUT: Electric Motor, 3 phases, P<sub>el</sub> and mechanical data

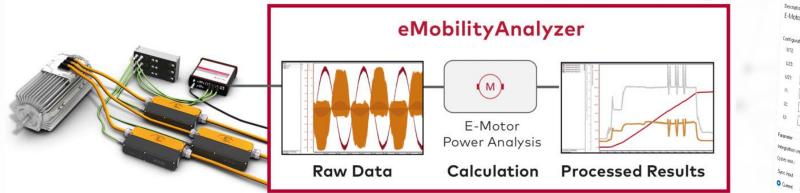


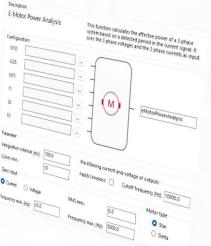


### Power Analysis with Vector-CSM eMobility Measurement System

Vector completes the measurement system with data acquisition systems providing the

eMobilityAnalyzer fast function library with Power Analyzer functionality





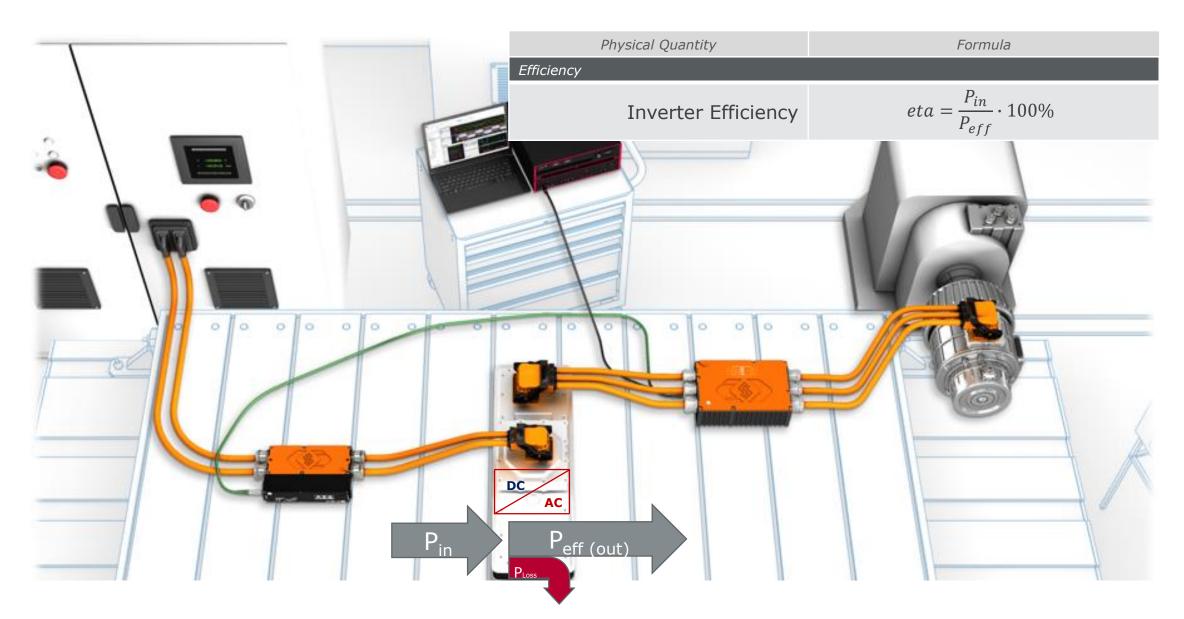
#### Available in CANape, vMeasure, vSignalyzer

- Measure power along with
  - > Signals from ECUs, vehicle bus, all kinds of further analog sensors
  - > Context information like GPS, video

All precisely synchronized and stored to the same measurement file

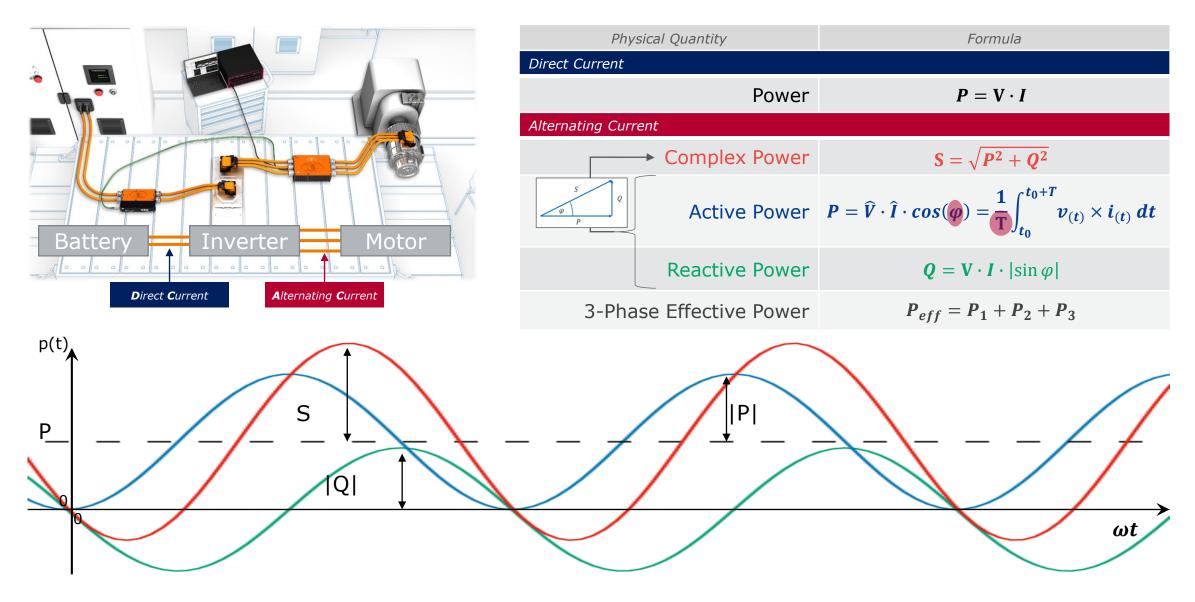


### Efficiency is the Ratio of Input vs. Output Power

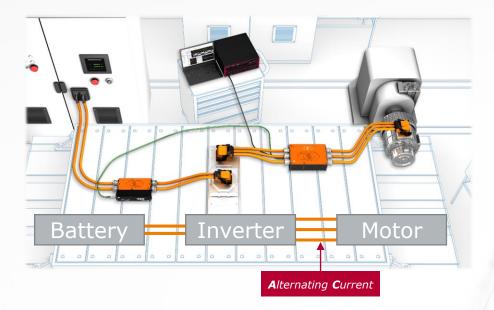




#### Indirect Power Measurement by Current and Voltage Measurement

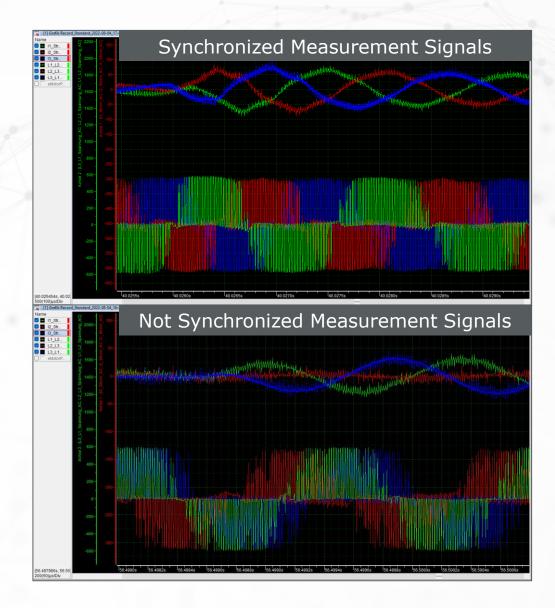


#### Challenges at AC Power Measurement – Synchronization

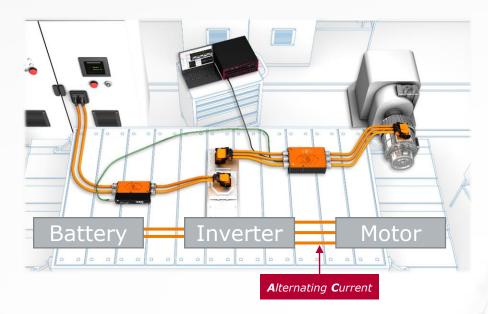


The phase angle  $\varphi$  must be accurately measured so requirements to time synchronous acquisition are very high to avoid

- shifts by time inaccuracy
- any variation in system latency on the different signals acquisition path's
- Precise Synchronization of current and voltage measurement is a MUST for power calculations

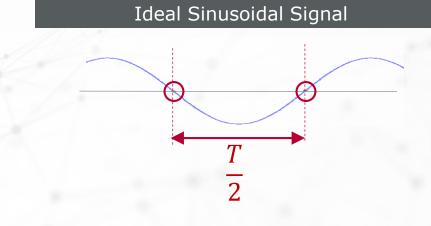


### Challenges at AC Power Measurement – Frequency Detection

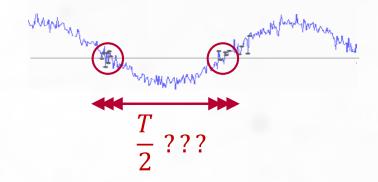


- The frequency f by period time T detection  $(f = \frac{1}{T})$
- Detection of T in noisy signals is a challenge
  - Zero crossing difficult to determine

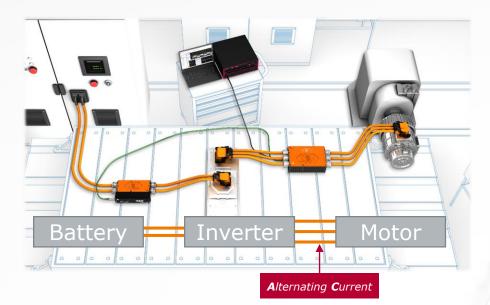
 Sophisticated statistical algorithms are required to determine period time / frequency



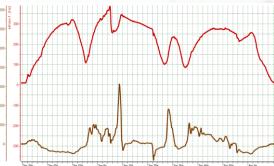
#### Real Noisy Measurement Signal



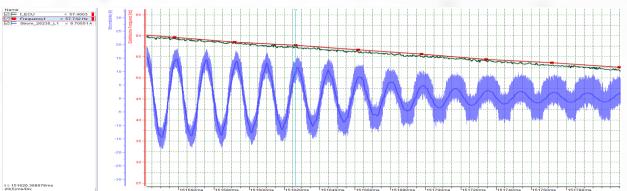
#### Challenges at AC Power Measurement – Highly Dynamic Frequency Changes



- Very dynamic vehicle operation conditions continuously changes
  - > Acceleration
  - > Breaking
  - > Recuperation
  - > Load changes
  - > Direction changes
  - > Force feed back from road, ...

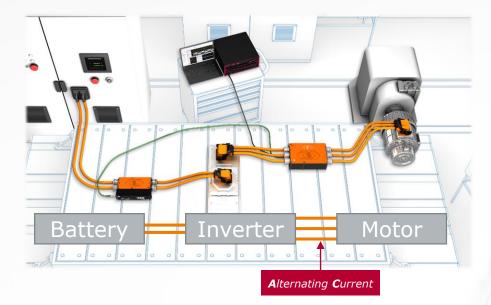


Frequency and Amplitudes are not steady state, they are changing very dynamically by load and speed



► Frequency detection must be stable/fast enough to follow highly dynamic changes

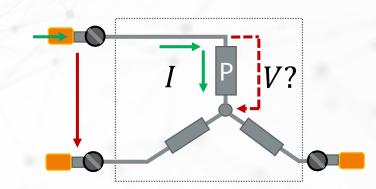
### Challenge eMotor Power Analysis



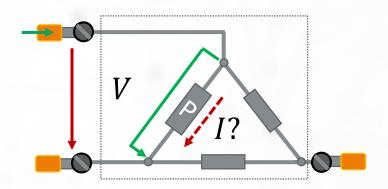
Accessible measurement points for current and voltage measurement cannot be used directly for power calculation.

The Y-delta transformation or its inverse required to calculate the respective currents and voltages of windings

### Star Motor



Delta Motor





#### Laboratory Power Analyser

### **Conventional Tools for Power Analysis**

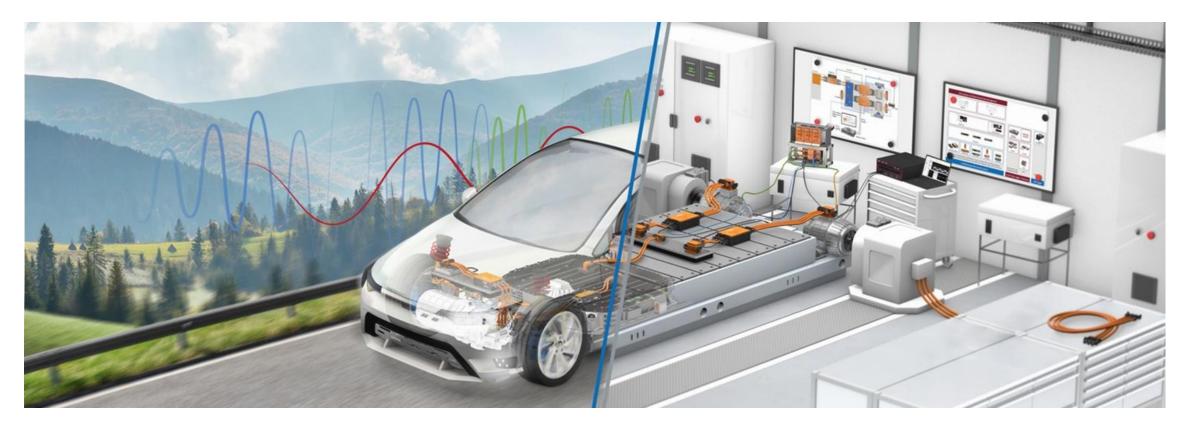
- Power analyzer are typically
  - Very precise
  - Made for In-lab usage
  - Limited synchronization to further signal sources
    - > ECUs
    - > Vehicle Bus Signals
    - > ...
  - Missing context information
  - Challenging offline analysis







### Power Analysis with Vector-CSM eMobility Measurement System



- ► All equipment is capable for On-Road Vehicle Trials and Laboratory use cases
- ▶ Vector Smart Logger can run the measurements fully automated in On-Road Tests
- And automated Data Analysis and Reporting can be realized with Vectors Measurement Data Management Tool vMDM